

# Nonlinear Control Systems

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## 3. Fundamental properties

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## Example

Consider the system

$$\dot{x} = f(t, x), \quad x(t_0) = x_0$$

- Does it have a solution over an interval  $[t_0, t_1]$ ?

That is, does exist a continuous function  $x : [t_0, t_1] \rightarrow \mathbb{R}^m$  such that  $\dot{x}(t)$  is defined and satisfies  $\dot{x}(t) = f(t, x(t))$ ,  $\forall t \in [t_0, t_1]$ ?

- Is it unique? or is possible to have more than one solution?
- ... and if we restrict  $f(t, x)$  to be continuous in  $x$  and piecewise continuous in  $t$ . Is this sufficient to guarantee existence and uniqueness?

No!, e.g.

$$\dot{x} = x^{1/3}, \quad x(0) = 0$$

It has solution  $x(t) = \left(\frac{2t}{3}\right)^{3/2}$ .

But is not unique, since  $x(t) = 0$  is another solution!

## Lipschitz condition

A function  $f(x)$  is said to be *locally Lipschitz* on a domain (open and connected set)  $D \subset \mathbb{R}^n$  if each point of  $D$  has a neighborhood  $D_0$  such that  $f(\cdot)$  satisfies

$$\|f(x) - f(y)\| \leq L \|x - y\|, \quad \forall x, y \in D_0$$

(with the same Lipschitz constant  $L$ ). The same terminology is extended to a function  $f(t, x)$ , provided that the Lipschitz constant holds uniformly in  $t$  for all  $t$  in a given interval.

*Remark:* For  $f : \mathbb{R} \rightarrow \mathbb{R}$ , we have

$$\frac{|f(x) - f(y)|}{|x - y|} \leq L$$

which means that a straight line joining any two points of  $f(\cdot)$  cannot have a slope whose absolute value is greater than  $L$ .

### Example

$f(x) = x^{1/3}$  is not locally Lipschitz at  $x = 0$  since  $f'(x) = \frac{1}{3}x^{-2/3} \rightarrow \infty$  as  $x \rightarrow 0$ .

## Existence and Uniqueness

### Theorem 3.1 - Local Existence and Uniqueness

Let  $f(t, x)$  be piecewise continuous in  $t$  and satisfy the Lipschitz condition

$$\|f(t, x) - f(t, y)\| \leq L \|x - y\|$$

$\forall x, y \in B = \{x \in \mathbb{R}^n : \|x - x_0\| \leq r\}, \forall t \in [t_0, t_1]$ . Then, there exists some  $\delta > 0$  such that the state equation  $\dot{x} = f(t, x)$  with  $x(t_0) = x_0$  has a unique solution over  $[t_0, t_0 + \delta]$ .

### Theorem 3.2 - Global Existence and Uniqueness

Suppose that  $f(t, x)$  is piecewise continuous in  $t$  and satisfies

$$\|f(t, x) - f(t, y)\| \leq L \|x - y\|, \quad \forall x, y \in \mathbb{R}^n, \forall t \in [t_0, t_1]$$

Then, the state equation  $\dot{x} = f(t, x)$ , with  $x(t_0) = x_0$ , has a unique solution over  $[t_0, t_1]$ .

## Existence and Uniqueness

### Lemma 3.2

If  $f(t, x)$  and  $\left[\frac{\partial f}{\partial x}\right]_{(t,x)}$  are continuous on  $[a, b] \times D$  for some domain  $D \subset \mathbb{R}^n$ , then  $f$  is locally Lipschitz in  $x$  on  $[a, b] \times D$ .

### Lemma 3.3

If  $f(t, x)$  and  $\left[\frac{\partial f}{\partial x}\right]_{(t,x)}$  are continuous on  $[a, b] \times \mathbb{R}^n$ , then  $f$  is globally Lipschitz in  $x$  on  $[a, b] \times \mathbb{R}^n$  if and only if  $\left[\frac{\partial f}{\partial x}\right]$  is uniformly bounded on  $[a, b] \times \mathbb{R}^n$ .

## Examples

1.

$$\dot{x} = A(t)x + g(t) = f(t, x) \quad (1)$$

with  $A(t)$ ,  $g(t)$  piecewise continuous functions of  $t$ .

$$\begin{aligned} \|f(t, x) - f(t, y)\| &= \|A(t)x + g(t) - (A(t)y + g(t))\| \\ &= \|A(t)(x - y)\| \leq \|A(t)\| \|x - y\| \end{aligned}$$

Note that for any finite interval of time  $[t_0, t_1]$ , the elements of  $A(t)$  are bounded. Thus  $\|A(t)\| \leq a$  for any induced norm and

$$\|f(t, x) - f(t, y)\| \leq a \|x - y\|$$

Therefore, from Theorem 3.1 we conclude that (1) has a unique solution over  $[t_0, t_1]$ . Since  $t_1$  can be arbitrarily large it follows that the system has a unique solution  $\forall t \geq t_0$ . There is no finite escape time.

## Examples

2.

$$\dot{x} = -x^3 = f(x), \quad x \in \mathbb{R} \quad (2)$$

Is it globally Lipschitz?

No! From Lemma 3.3,  $f(x)$  is continuous but the Jacobian  $\frac{\partial f}{\partial x} = -3x^2$  is not globally bounded. Nevertheless,  $\forall x(t_0) = x_0$ , (2) has the unique solution

$$x(t) = \operatorname{sgn}(x_0) \sqrt{\frac{x_0^2}{1 + 2x_0^2(t - t_0)}}$$

3.

$$\dot{x} = -x^2, \quad x(0) = -1 \quad (3)$$

From Lemma 3.2 we conclude that is locally Lipschitz in any compact subset of  $\mathbb{R}$  because  $f(x)$  and  $\frac{\partial f}{\partial x}$  are continuous. Hence, there exists a unique solution over  $[0, \delta]$  for some  $\delta > 0$ . In particular the solution is

$$x(t) = \frac{1}{t - 1}$$

and only exists over  $[0, 1)$ , i.e, there is finite escape time at  $t = 1$ !

## Uniqueness and Existence

### Theorem 3.3

Let  $f(t, x)$  be piecewise continuous in  $t$  and locally Lipschitz in  $x$  for all  $t \geq t_0$  and all  $x \in D \subset \mathbb{R}^n$ . Let  $W$  be a compact subset of  $D$ ,  $x_0 \in W$  and suppose it is known that every solution of

$$\dot{x} = f(t, x), \quad x(t_0) = x_0$$

lies entirely in  $W$ . Then, there is a unique solution that is defined for all  $t \geq t_0$ .

### Proof.

By Theorem 3.1, there is a unique solution over  $[t_0, t_0 + \delta]$ . Let  $[t_0, T)$  be its maximum interval of existence. We would like to show that  $T = \infty$ . Suppose that is not, i.e.,  $T$  is finite. Then the solution must leave any compact subset of  $D$ . But this is a contradiction, because  $x$  never leaves the compact set  $W$ . Thus we can conclude that  $T = \infty$ .  $\square$

## Example

Returning to the example

$$\dot{x} = -x^3$$

It is locally Lipschitz in  $\mathbb{R}$ . For any initial condition  $x(0) = x_0 \in \mathbb{R}$ , the solution cannot leave the compact set  $W = \{x \in \mathbb{R} : |x| \leq x_0\}$  because for any instant of time

- if  $x > 0$  then  $\dot{x} < 0$
- if  $x < 0$  then  $\dot{x} > 0$

Thus, *without computing explicitly the solution* we can conclude from Theorem 3.3 that the system has a unique solution for all  $t \geq 0$ .

## Continuous dependence on initial conditions and parameters

Consider the following nominal model

$$\dot{x} = f(t, x, \lambda_0) \quad (4)$$

where  $\lambda_0 \in \mathbb{R}^p$  denotes the nominal vector of constant parameters of the model and  $x \in \mathbb{R}^n$  is the state.

- Let  $y(t)$  be a solution of (4) that starts at  $y(t_0) = y_0$  and is defined on the interval  $[t_0, t_1]$ .
- Let  $z(t)$  be a solution of  $\dot{x} = f(t, x, \lambda)$  defined on  $[t_0, t_1]$  with  $z(t_0) = z_0$ .

*When does  $z(t)$  remains close to  $y(t)$ ?*

Or in other words, is the solution continuous dependent on the initial condition and parameter  $\lambda$ ? That is,

$$\forall \varepsilon > 0 \exists \delta > 0 : \|z_0 - y_0\| < \delta, \|\lambda - \lambda_0\| < \delta \Rightarrow \|z(t) - y(t)\| < \varepsilon, \forall t \in [t_0, t_1]$$

## Continuous dependence on initial conditions and parameters

### Theorem 3.4

Let  $f(t, x)$  be piecewise continuous in  $t$  and Lipschitz in  $x$  (with a Lipschitz constant  $L$ ) on  $[t_0, t_1] \times W$ , where  $W \subset \mathbb{R}^n$  is an open connected set. Let  $y(t)$  and  $z(t)$  be solutions of

$$\begin{aligned} \dot{y} &= f(t, y), & y(t_0) &= y_0 \\ \dot{z} &= f(t, z) + g(t, z), & z(t_0) &= z_0 \end{aligned}$$

such that  $y(t), z(t) \in W, \forall t \in [t_0, t_1]$ . Suppose that

$$\|g(t, z)\| \leq \mu, \quad \forall (t, z) \in [t_0, t_1] \times W$$

for some  $\mu > 0$ . Then

$$\|y(t) - z(t)\| \leq \|y_0 - z_0\| e^{L(t-t_0)} + \frac{\mu}{L} \left( e^{L(t-t_0)} - 1 \right), \quad \forall t \in [t_0, t_1]$$

Proof

$$y(t) = y_0 + \int_{t_0}^t f(\tau, y(\tau)) d\tau$$

$$z(t) = z_0 + \int_{t_0}^t [f(\tau, z(\tau)) + g(\tau, z(\tau))] d\tau$$

Subtracting and taking norms yields

$$\begin{aligned} \|y(t) - z(t)\| &\leq \|y_0 - z_0\| + \int_{t_0}^t \|f(\tau, y(\tau)) - f(\tau, z(\tau))\| d\tau + \int_{t_0}^t \|g(\tau, z(\tau))\| d\tau \\ &\leq \underbrace{\|y_0 - z_0\|}_{\gamma} + \int_{t_0}^t L \|y(\tau) - z(\tau)\| d\tau + \mu(t - t_0) \end{aligned}$$

Applying the Gronwall-Bellman inequality, yields

$$\|y(t) - z(t)\| \leq \gamma + \mu(t - t_0) + \int_{t_0}^t L[\gamma + \mu(\tau - t_0)] e^{L(t-\tau)} d\tau$$

Integrating the right-hand side by parts ( $\int uv' = uv - \int vu'$ ) we obtain

$$\begin{aligned} \|y(t) - z(t)\| &\leq \gamma + \mu(t - t_0) - \gamma - \mu(t - t_0) + \gamma e^{L(t-t_0)} + \int_{t_0}^t \mu e^{L(t-s)} ds \\ &= \gamma e^{L(t-t_0)} + \frac{\mu}{L} (e^{L(t-t_0)} - 1) \end{aligned}$$

### Theorem 3.5 - Continuity of solutions

Let  $f(t, x, \lambda)$  be continuous in  $(t, x, \lambda)$  and locally Lipschitz in  $x$  on  $[t_0, t_1] \times D \times \{\|\lambda - \lambda_0\| \leq c\}$ , where  $D \subset \mathbb{R}^n$  is an open connected set. Let  $y(t, \lambda_0)$  be a solution of

$$\dot{x} = f(t, x, \lambda_0),$$

with  $y(t_0, \lambda_0) = y_0 \in D$ . Suppose  $y(t, \lambda_0)$  is defined and belongs to  $D$  for all  $t \in [t_0, t_1]$ . Then, given  $\epsilon > 0$ , there is  $\delta > 0$  such that if

$$\|z_0 - y_0\| < \delta, \quad \|\lambda - \lambda_0\| < \delta$$

then there is a unique solution  $z(t, \lambda)$  of  $\dot{x} = f(t, x, \lambda)$  defined on  $[t_0, t_1]$ , with  $z(t_0, \lambda) = z_0$  such that  $\|z(t, \lambda) - y(t, \lambda_0)\| < \epsilon, \forall t \in [t_0, t_1]$

**Proof.**

$$\dot{z} = f(t, z, \lambda_0) + \underbrace{f(t, z, \lambda) - f(t, z, \lambda_0)}_{g(t, z)}$$

By continuity  $\forall \mu > 0, \exists \delta > 0$ :

$$\|\lambda - \lambda_0\| < \delta \Rightarrow \|g(t, z)\| \leq \mu$$

Therefore, using Theorem 3.4 we conclude Theorem 3.5 by noticing that  $\|y_0 - z_0\|$  and  $\mu$  can be chosen arbitrarily small.

□

## Comparison Principle

Quite often when we study the state equation  $\dot{x} = f(t, x)$  we need to compute bounds on the solution  $x(t)$ . For that we have

- Gronwall-Bellman inequality
- The comparison Lemma  $\rightarrow$  Compares the solution of the differential inequality  $\dot{v}(t) \leq f(t, v(t))$  with the solution of  $\dot{u}(t) = f(t, u)$ . Moreover,  $v(t)$  is not needed to be differentiable.

### Definition

*Upper right-hand derivative*

$$D^+v(t) = \limsup_{h \rightarrow 0^+} \frac{v(t+h) - v(t)}{h}$$

The following properties hold:

- if  $v(t)$  is differentiable at  $t$  then  $D^+v(t) = \dot{v}(t)$
- if  $\frac{1}{h} |v(t+h) - v(t)| \leq g(t, h)$  and  $\lim_{h \rightarrow 0^+} g(t, h) = g_0(t)$ , then  $D^+v(t) \leq g_0(t)$

## Comparison Principle

### Lemma 3.4 - Comparison Lemma

Let

$$\dot{u} = f(t, u), \quad u(t_0) = u_0, \quad \mu \in \mathbb{R}$$

where  $f(t, u)$  is continuous in  $t$  and locally Lipschitz in  $u$ , for all  $t \geq 0$  and  $u \in J \subset \mathbb{R}$ . Let  $[t_0, T)$  ( $T$  can be  $\infty$ ) be the maximal interval of existence of the solution  $u(t) \in J$ . Let  $v(t)$  be a continuous function that satisfies

$$D^+v(t) \leq f(t, v), \quad v(t_0) \leq u_0$$

with  $v(t) \in J$  for all  $t \in [t_0, T)$ . Then,  $v(t) \leq u(t)$ ,  $\forall t \in [t_0, T)$

## Example

Show that the solution of

$$\dot{x} = f(x) = -(1 + x^2)x, \quad x(0) = a$$

is unique and defined for all  $t \geq 0$ .

Because  $f(x)$  is locally Lipschitz it has a unique solution on  $[0, t_1]$  for some  $t_1 > 0$ . Let  $v(t) = x^2(t)$ . Then

$$\dot{v}(t) \leq -2v(t), \quad v(0) = a^2$$

Let  $u(t)$  be the solution of

$$\dot{u} = -2u, \quad u(0) = a^2 \longrightarrow u(t) = a^2 e^{-2t}$$

Then, by comparison lemma the solution  $x(t)$  is defined  $\forall t \geq 0$  and satisfies

$$|x(t)| = \sqrt{v(t)} \leq |a| e^{-t}, \quad \forall t \geq 0$$

By Theorem 3.3 it follows that the solution is unique and defined for all  $t \geq 0$ .