

# **Industrial Automation**

## **(Automação de Processos Industriais)**

### **Analysis of Discrete Event Systems**

### **Complexity and Decidability**

<http://users.isr.ist.utl.pt/~jag/courses/api1516/api1516.html>

Slides 2010/2011 Prof. Paulo Jorge Oliveira

Rev. 2011-2015 Prof. José Gaspar

## **Syllabus:**

**Chap. 6 – Discrete Event Systems [2 weeks]**

...

**Chap. 7 – Analysis of Discrete Event Systems [2 weeks]**

**Properties of DESs.**

**Methodologies to analyze DESs:**

- \* The Reachability tree.**
- \* The Method of Matrix Equations.**

...

**Chap. 8 – DESs and Industrial Automation [1 week]**

## Some pointers to Discrete Event Systems

History: <http://prosys.changwon.ac.kr/docs/petrinet/1.htm>

Tutorial: <http://vita.bu.edu/cgc/MIDEDS/>  
<http://www.daimi.au.dk/PetriNets/>

Analyzers,  
and  
Simulators: <http://www.ppgia.pucpr.br/~maziero/petri/arp.html> (in Portuguese)  
<http://wiki.daimi.au.dk:8000/cpntools/cpntools.wiki>  
<http://www.informatik.hu-berlin.de/top/pnk/download.html>

Bibliography: \* Cassandras, Christos G., "**Discrete Event Systems - Modeling and Performance Analysis**", Aksen Associates, 1993.  
\* Peterson, James L., "**Petri Net Theory and the Modeling of Systems**", Prentice-Hall, 1981  
\* **Petri Nets and GRAFCET: Tools for Modelling Discrete Event Systems**  
R. DAVID, H. ALLA, New York : PRENTICE HALL Editions, 1992

## Complexity and Decidability

*The reachability tree and matrix equation techniques allow properties of **safeness**, **boundedness**, **conservation**, and **coverability** to be determined for Petri nets. In particular, a necessary condition for reachability is established.*

*However, these techniques are not sufficient to solve several other problems, especially **liveness**, **reachability (sufficient condition)**, and **equivalence**.*

*[Peterson 81, ch5]*

*In the following: we will discuss the complexity and decidability of the problems not solved.*

## Complexity and Decidibility

- Till the end of this chapter, *problem* is intended as a question with yes/no answer, e.g. “ does  $\mu' \in R(C, \mu) \quad \forall C, \mu, \mu' ?$  ”
- A *problem* is *undecidable* if it is proven that no algorithm to solve it exists.

*An example of a undecidable problem is the stop of a Turing machine (TM):*

*“Will the TM stop for the code  $n$  after using the number  $m$ ?”.*

- For *decidable* problems, the *complexity* of the solutions has to be taken into account, that is, the computational cost in terms of memory and time.

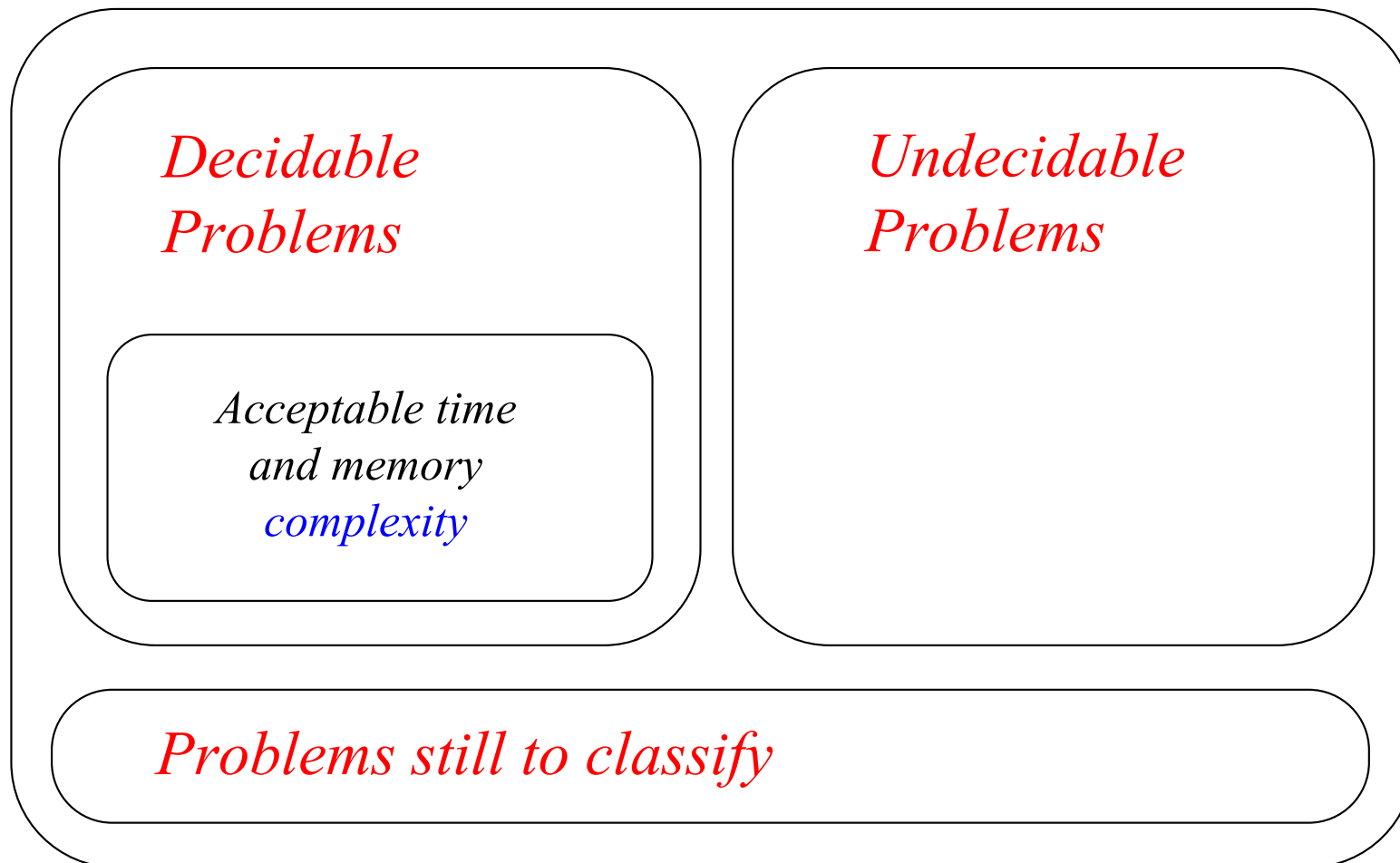
*Basic example: a multiplication of numbers has solution (algorithm taught in the school),*

*but the complexity was different in the arabic and latin civilizations*

*(how to do a multiplication using roman numbers?)*

## Complexity and Decidibility

*Problems with yes or no answers*



## Reducibility

One *benefits of reducibility* when to solve a given problem it is *possible to reduce it to another problem with known solution.*

**Theorem:** Assume that the problem  $A$  is **reducible** to problem  $B$ ,  
then an instance of  $A$  can be transformed in an instance of  $B$  and:

- **If  $B$  is decidable then  $A$  is decidable.**
- **If  $A$  is undecidable then  $B$  is undecidable.**

## Reducibility

**Equality Problem:** Given two marked Petri nets

$C_1=(P_1, T_1, I_1, O_1)$  and  $C_2=(P_2, T_2, I_2, O_2)$ , with markings  $\mu_1$  e  $\mu_2$ , respectively,  
is  $R(C_1, \mu_1) = R(C_2, \mu_2)$  ?

**Subset Problem:** Given two marked Petri nets

$C_1=(P_1, T_1, I_1, O_1)$  and  $C_2=(P_2, T_2, I_2, O_2)$ , with markings  $\mu_1$  e  $\mu_2$ , respectively,  
is  $R(C_1, \mu_1) \subseteq R(C_2, \mu_2)$  ?

The **equality** problem is **reducible** to the **subset** problem  
(equality is obtained by proving that each set is a subset of the other)



## Decidibility

If a problem is  $\approx$  **undecidable** does it mean that it is not solvable?

No, while not proved to be undecidable there is hope it can be solved!

Classical example, Fermat Last Theorem:

Does  $x^n + y^n = z^n$  have a solution for  $n > 2$  and nontrivial integers  $x, y$  e  $z$ ?

Now, it is known that the problem is impossible, i.e. its answer is *No*. The problem remained  $\approx$  undecidable for more than 2 centuries (solution proven in 1998).

*The Turing Machine (TM) Halting problem is undecidable.*

If it were decidable, for instance the Fermat last theorem would have been proven long time ago, i.e. there would be an algorithm (*TM* with code  $n$ ) that computing all combinations of  $x, y, z$  and  $n > 2$  (number  $m$ ) to find a solution verifying  $x^n + y^n = z^n$ .

## Reachability Problems

Given a Petri net  $C=(P,T,I,O)$  with initial marking  $\mu$

### Reachability Problem:

Considering a marking  $\mu'$ , does  $\mu' \in R(C, \mu)$  ?

### Sub-marking Reachability Problem:

Given the marking  $\mu'$  and a subset  $P' \subseteq P$ , exists  $\mu'' \in R(C, \mu)$  such that  $\mu''(p_i) = \mu'(p_i) \forall p_i \in P'$ ?

### Zero Reachability Problem:

Given the marking  $\mu'=(0 \ 0 \ \dots \ 0)$ , does  $\mu' \in R(C, \mu)$  ?

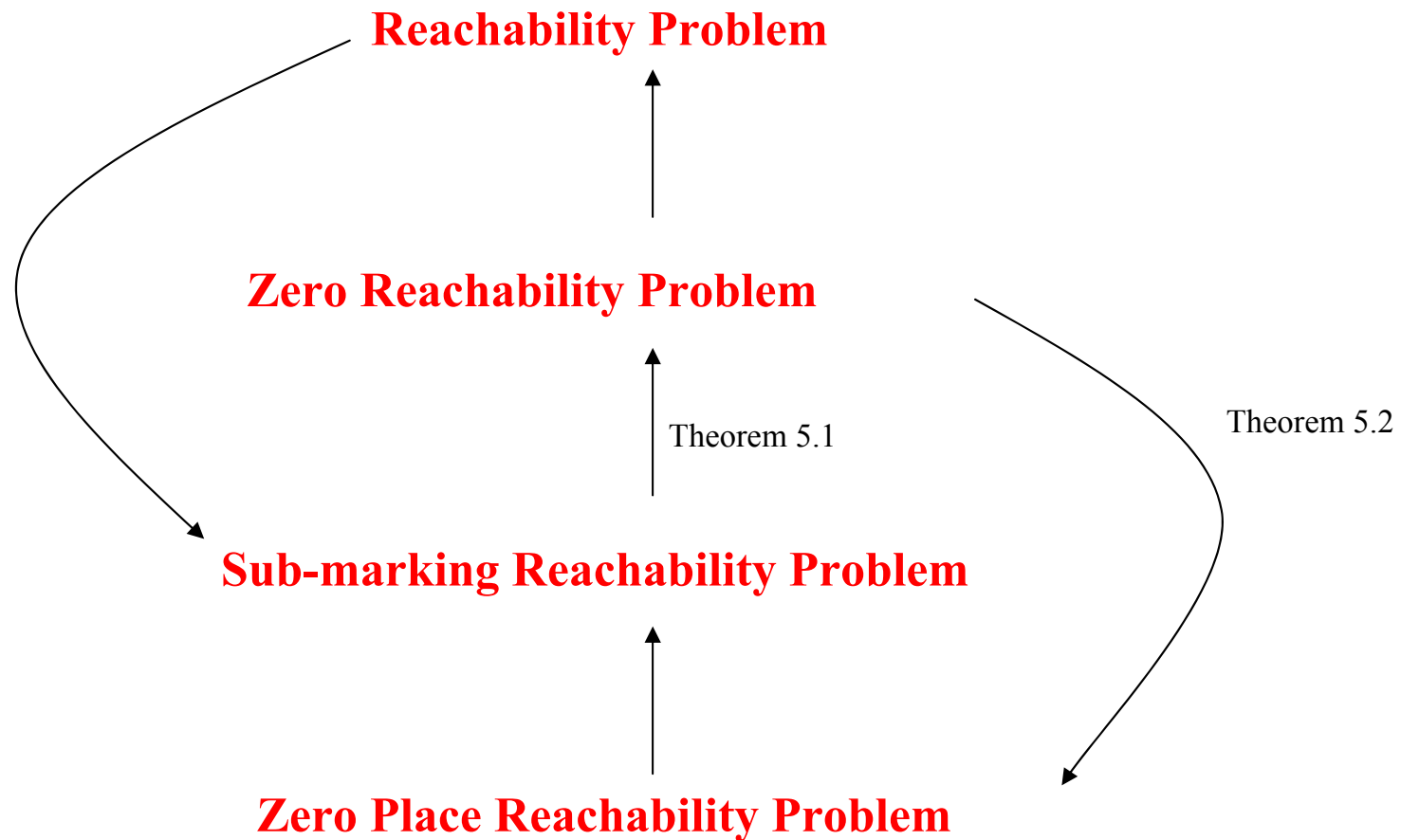
### Zero Place Reachability Problem:

Given the place  $p_i \in P$ , does  $\mu' \in R(C, \mu)$  with  $\mu'(p_i) = 0$  ?

# Reachability Problems

Legend:

$A \rightarrow B$  means A is reducible to B



## Reachability Problems

Theorem 5.3: The following reachability problems are equivalent:

- **Reachability Problem;**
- **Zero Reachability Problem;**
- **Sub-marking Reachability Problem;**
- **Zero Place Reachability Problem.**

[Peterson81]

## Liveness and Reachability

(Given a Petri net  $C=(P,T,I,O)$  with initial marking  $\mu$ )

### Liveness Problem

Are all transitions  $t_j$  of  $T$  live?

### Transition Liveness Problem

For the transition  $t_j$  of  $T$ , is  $t_j$  live?

The **liveness** problem is **reducible** to the **transition liveness** problem. To solve the first it remains only to solve the second for the  $m$  Petri net transitions ( $\#T = m$ ).

## Liveness and Reachability

(Given a Petri net  $C=(P,T,I,O)$  with initial marking  $\mu$ )

Theorem 5.5: The problem of reachability is reducible to the liveness problem.

Theorem 5.6: The problem of liveness is reducible to the reachability problem.

Theorem 5.7: The following problems are **equivalent**:

- **Reachability problem**
- **Liveness problem**

## Decidibility results

Theorem 5.10: The sub-marking reachability problem is reducible to the reachable subsets of a Petri net.

Theorem 5.11: **The following problem is undecidable:**

- Subset problem for reachable sets of a Petri net

*They are all reducible to the famous Hilbert's 10th problem:*

*The solution of the Diophantine equation of  $n$  variables, with integer coefficients*

*$P(x_1, x_2, \dots, x_n) = 0$  is undecidable.*

*(proof by Matijasevic that it is undecidable in the late 1970s).*

## Decidibility

*"... most decision problems involving finite-state automata can be solved algorithmically in finite time, i.e., they are **decidable**. Unfortunately, many problems that are decidable for **finite state automata** are no longer decidable for **Petri nets**, reflecting a natural trade off between **decidability** and **model-richness**. (...) Overall, it is probably most helpful to think of Petri nets and automata as **complementary modeling approaches**, rather than competing ones."*

*[Cassandras 2008]*