

Spoken dialog systems as an application of POMDPs

Jason D. Williams

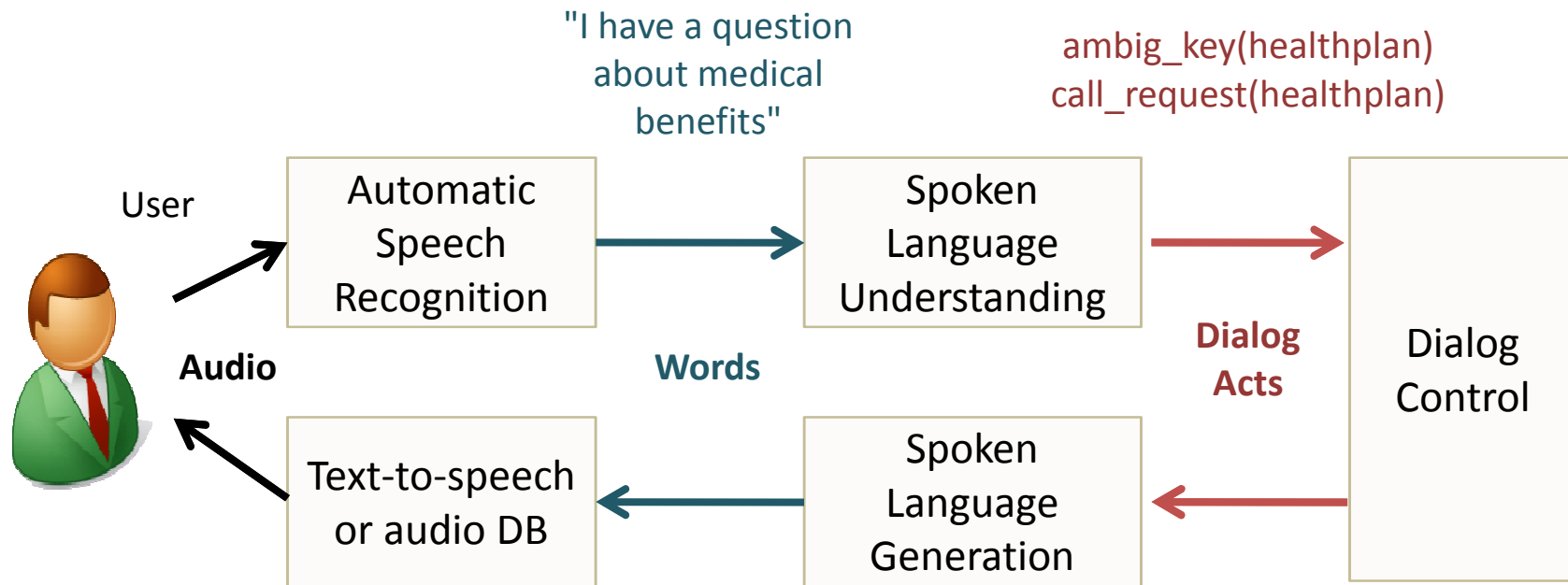


ICAPS Workshop – May 2010

What is a spoken dialog system?

A spoken dialogue system is a computer agent that interacts with people by understanding spoken language.

Speech recognition and spoken language understanding




"I have a question about medical benefits"

`ambig_key(healthplan)`
`call_request(healthplan)`

"Ok, health plans. Here is a list of choices, when you hear the one you want just say it: AT&T Benefits Center, HMOs, Dental, Vision, Flexible Spending Accounts, Health Savings Account, COBRA or other company Medical Plans."

`disambiguate(healthplan)`

Spoken dialogue systems come in many flavours

Input	Output	Example
Speech	Speech	Telephone technical support [1] 
Speech + ?GUI	Speech + ?GUI	In-car music control, navigation
Speech + GUI	Speech + GUI	Tutoring
Speech + GUI	Speech + GUI	Language learning
Speech + GUI	?Speech + GUI	TV program guide
Speech + GUI	?Speech + GUI	Mobile search interface
Speech + vision	Speech + robot/agent	Eldercare
Speech + vision	Speech + robot/agent	Automated receptionist

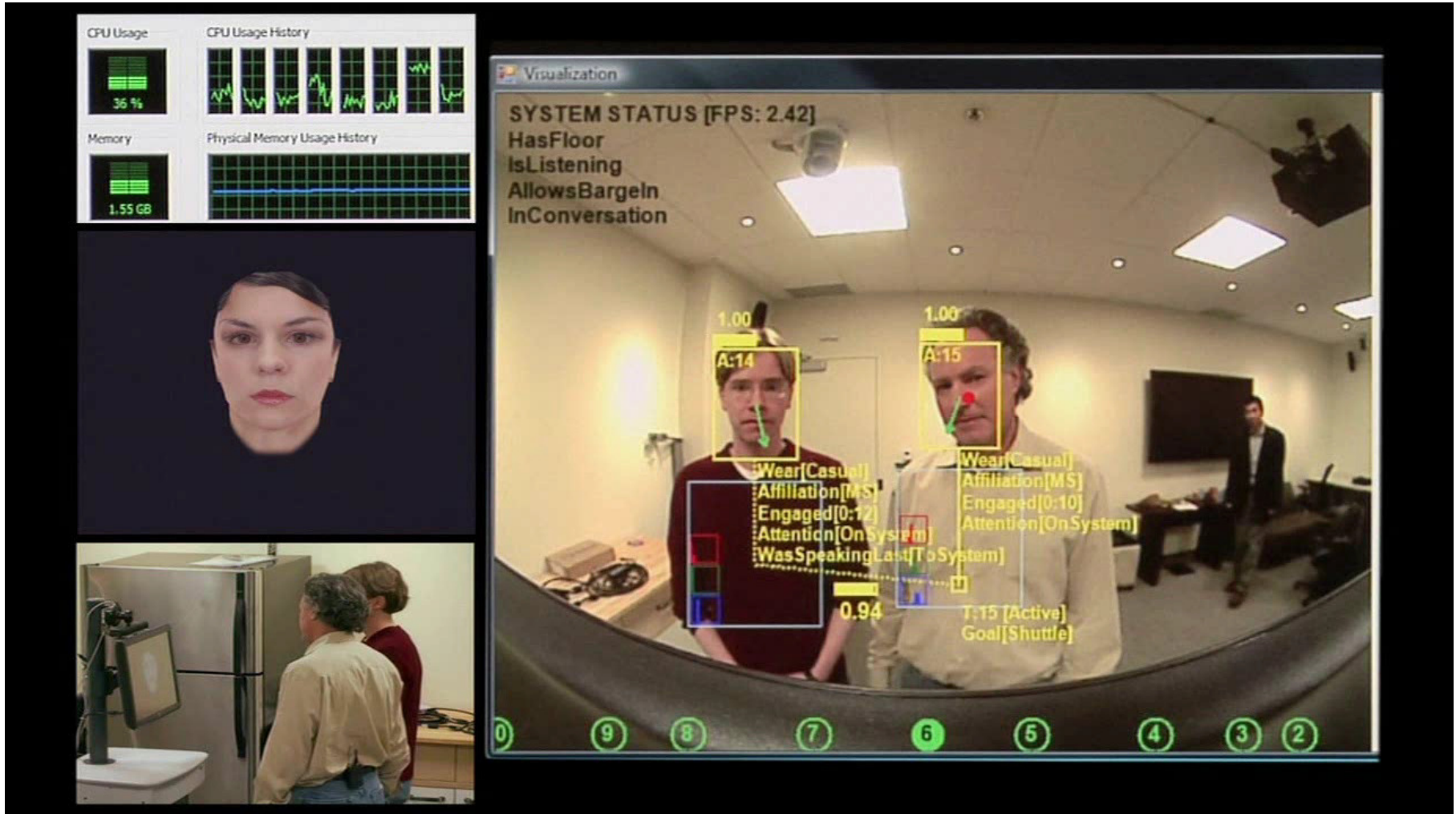
[1] Recording of a deployed dialog system, AT&T

In-car spoken dialogue system



Source: IBM

Automated receptionist



Bohus, D., Horvitz, E. (2009). Models for Multiparty Engagement in Open-World Dialog, in Proceedings of SIGdial'09, London, UK

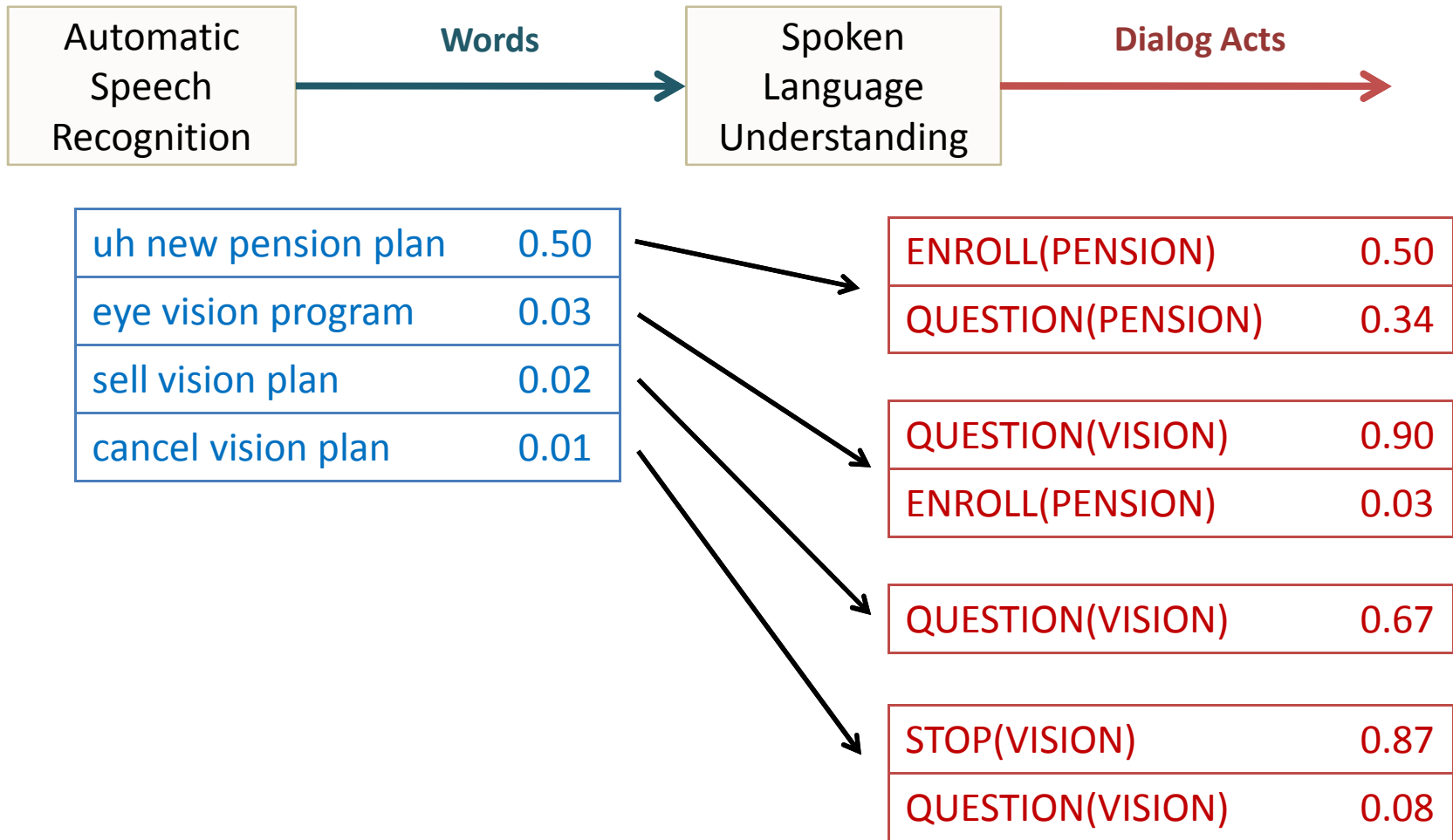
Outline

- Key challenges for building dialogue systems
- How dialogue systems are built today
- Casting a dialogue system as a POMDP
- "Growing up" to real-world systems
- Thoughts about the future

Challenges (among others)

1. Channel errors (ASR, SLU, turn-taking)
2. Curse of history
3. Theory of mind problem

Speech recognition and spoken language understanding



ASR/SLU errors are common

Grammar	Yes/no	City & state	How may I help you?
---------	--------	--------------	---------------------

Source: Two different deployed commercial applications running two different speech recognizers

ASR/SLU errors are common

Grammar	Yes/no	City & state	How may I help you?
In-grammar/ in-domain accuracy	99.8%	85.1%	89.5%

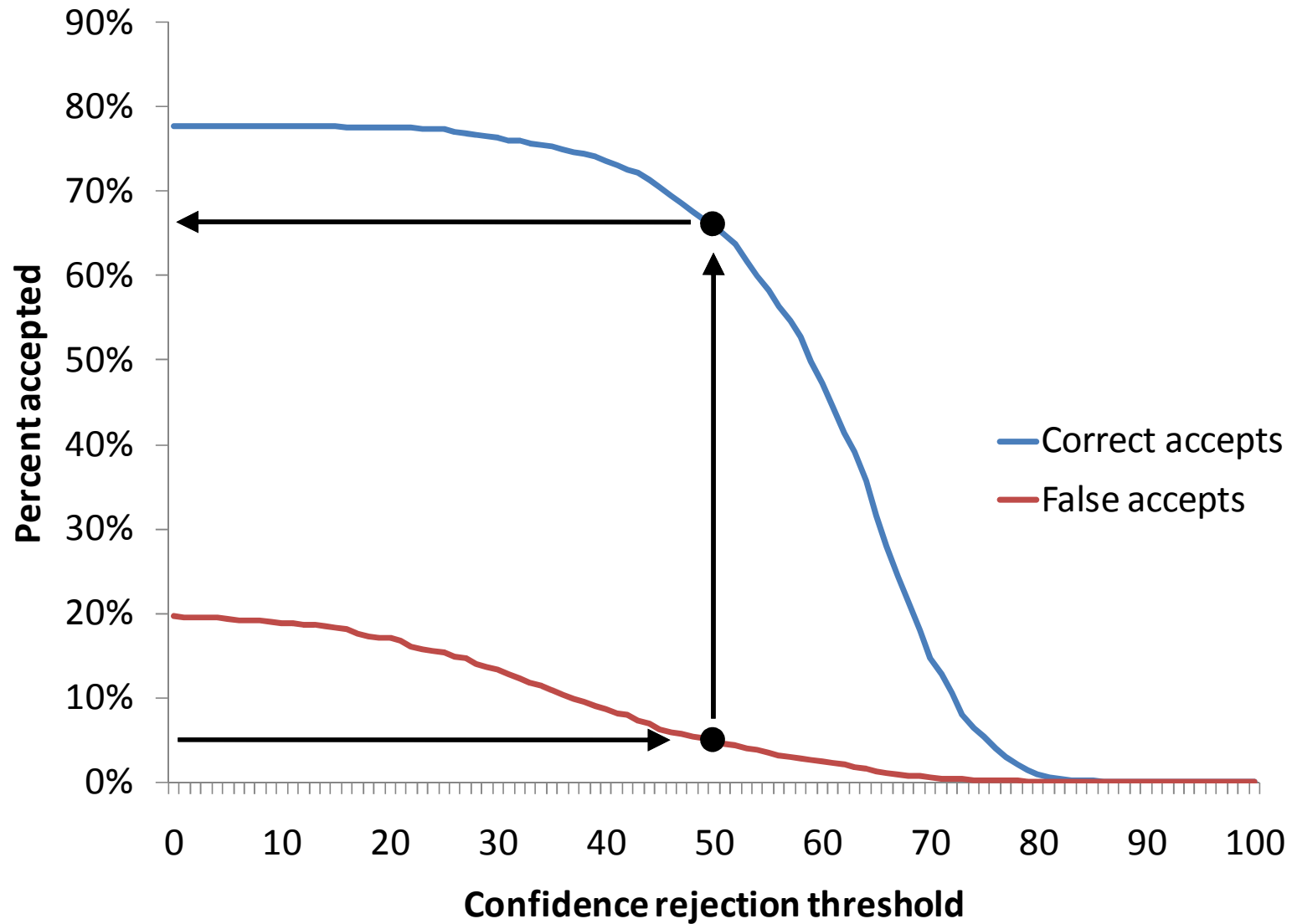
Source: Two different deployed commercial applications running two different speech recognizers

ASR/SLU errors are common

Grammar	Yes/no	City & state	How may I help you?
In-grammar/ in-domain accuracy	99.8%	85.1%	89.5%
% in-grammar/ in-domain	92.3%	91.0%	86.8%
Overall accuracy	92.1%	77.6%	77.7%

Source: Two different deployed commercial applications running two different speech recognizers

ASR errors are hard to detect



ASR/SLU errors are common

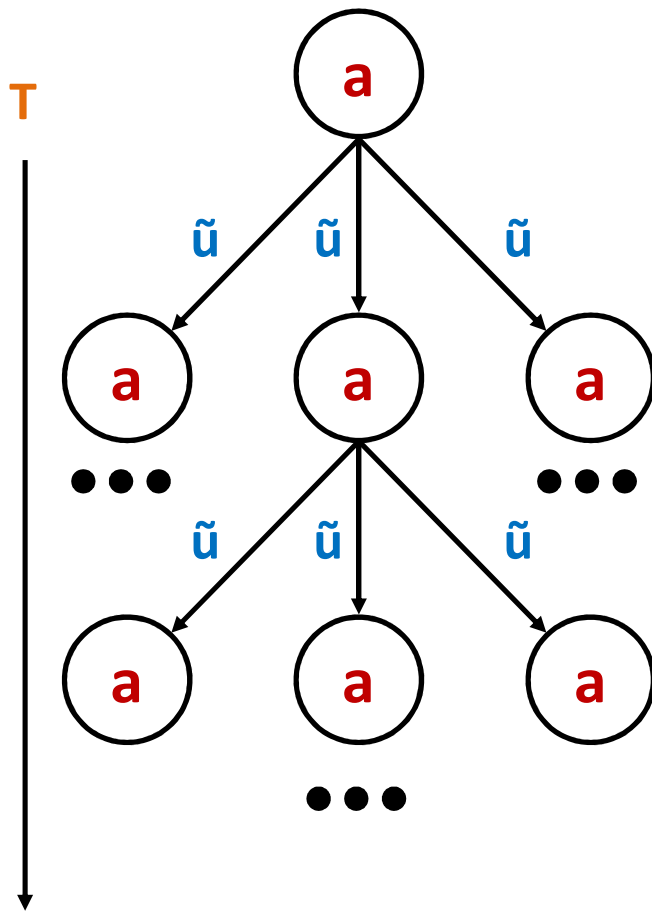
Grammar	Yes/no	City & state	How may I help you?
In-grammar/ in-domain accuracy	99.8%	85.1%	89.5%
% in-grammar/ in-domain	92.3%	91.0%	86.8%
Overall accuracy	92.1%	77.6%	77.7%
Accepted utts (False accepts)	89.6% (1.8%)	60.3% (4.9%)	73.3% (8.3%)

Source: Two different deployed commercial applications running two different speech recognizers

Curse of history

$A = \{\text{ask}(\text{first-name}), \text{confirm}(\text{last-name}=\text{williams}), \dots\}$

$\tilde{U} = \{\text{YES}, \text{JASON}, \text{WILLIAMS}, \dots\}$



$\sim A^{\tilde{U}^T}$ possible
assignments

Typical system:

$$A = 10^{10}$$

$$\tilde{U} = 10^{10}$$

$$T = 10$$

Curse of history

$$F(\tilde{u}_0, a_1, \tilde{u}_1, a_2, \tilde{u}_2, a_3, \tilde{u}_3, \dots, a_t, \tilde{u}_t) = a_{t+1}$$

Often it's more convenient to separate the *tracking* problem from the *action selection* problem:

Dialog state $s_t \approx (\tilde{u}_0, a_1, \tilde{u}_1, a_2, \tilde{u}_2, a_3, \tilde{u}_3, \dots, a_t, \tilde{u}_t)$

State tracking $s_{t+1} = G(s_t, a_t, \tilde{u}_n)$

Action selection $F(s_{t+1}) = a_{t+1}$

Now the problem is what to track in the dialog state s , and how to make use of it when choosing actions

The "theory of mind" problem

A real
human



**What can she/he/it
understand?**

Anything I
can explain

**How do I know what it
can understand?**

I'm used to
speaking to people

Users must think simultaneously about what language the system can understand, and what the system can do – they must form a "theory of mind" about the dialog system

Responses to "How may I help you?"

- Silences and hesitations while users think
 - 🔊 Leads to end-pointing problems
 - 🔊 Leads to users confusing themselves
- "Robot" language (hence examples, "speak naturally")
 - 🔊 Example 1
 - 🔊 Example 2
- Recognition errors confused with competences
 - 🔊 > "i need to sign up for a **get off** benefit" *[no parse]*
 - 🔊 > "i would like to enroll in a **get one**" *[no parse]*
 - 🔊 > "i would like to get help with my dental insurance" <HELP>
 - 🔊 > "dental insurance" <INSURANCE>

Source: Live calls, human resources dialog system, AT&T

How dialog systems are built today

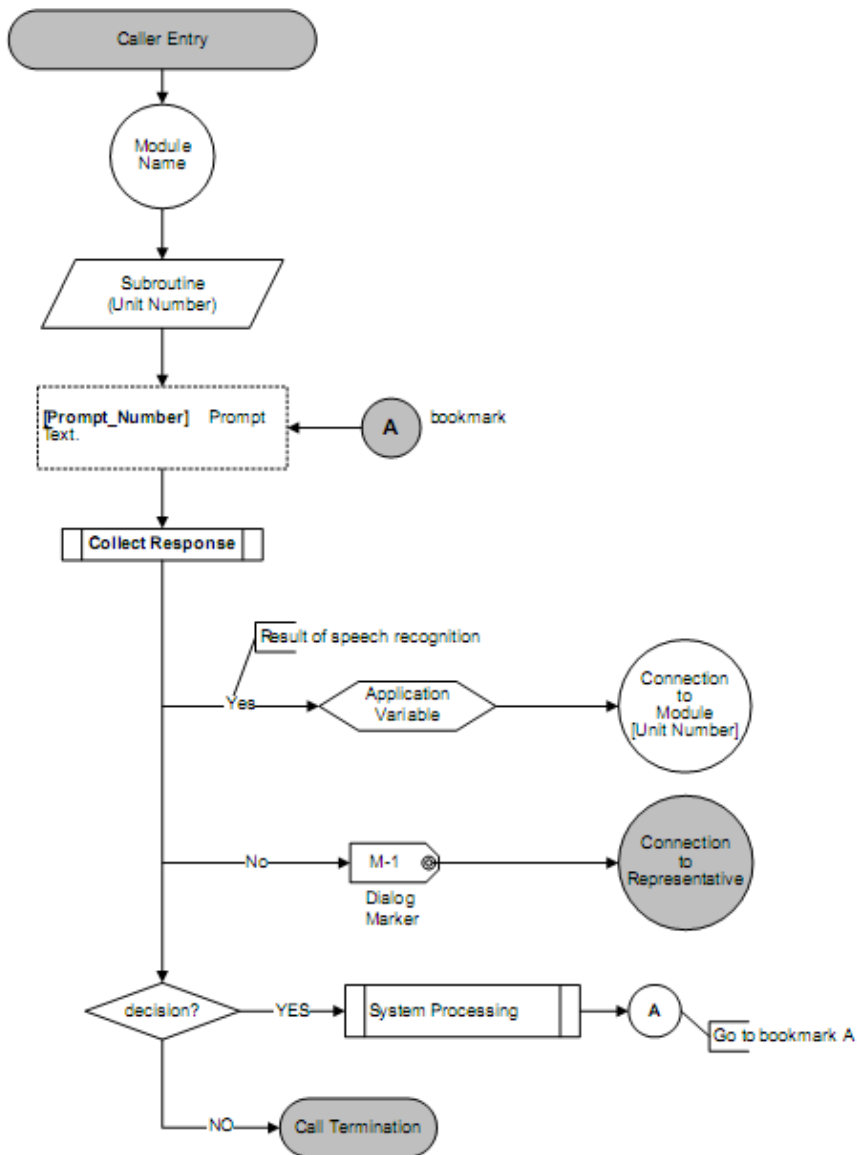
Spoken dialog systems as an application
of POMDPs

How dialog systems are built today

S =

reco[1] :	Jason Williams
conf[1]:	0.43
reco[2]:	Jay Wilpon
conf[2]:	0.05
reco[3]:	Jim Wilson
conf[3]:	0.01
name-tries:	2
confirmed-stat:	No
confirmed-tries:	0
confirmed-ID:	{}
match-count[1]:	1
match[1][1]:	jw4796
location[1][1]:	Florham Park
phone-types[1]:	{office, mobile}
phone-types[2]:	{office}
phone-types[3]:	{mobile}
caller-location:	New York
last-call:	Jay Wilpon

How dialog systems are built today



Typical commercial spoken dialog system contains ~100 pages of flowchart

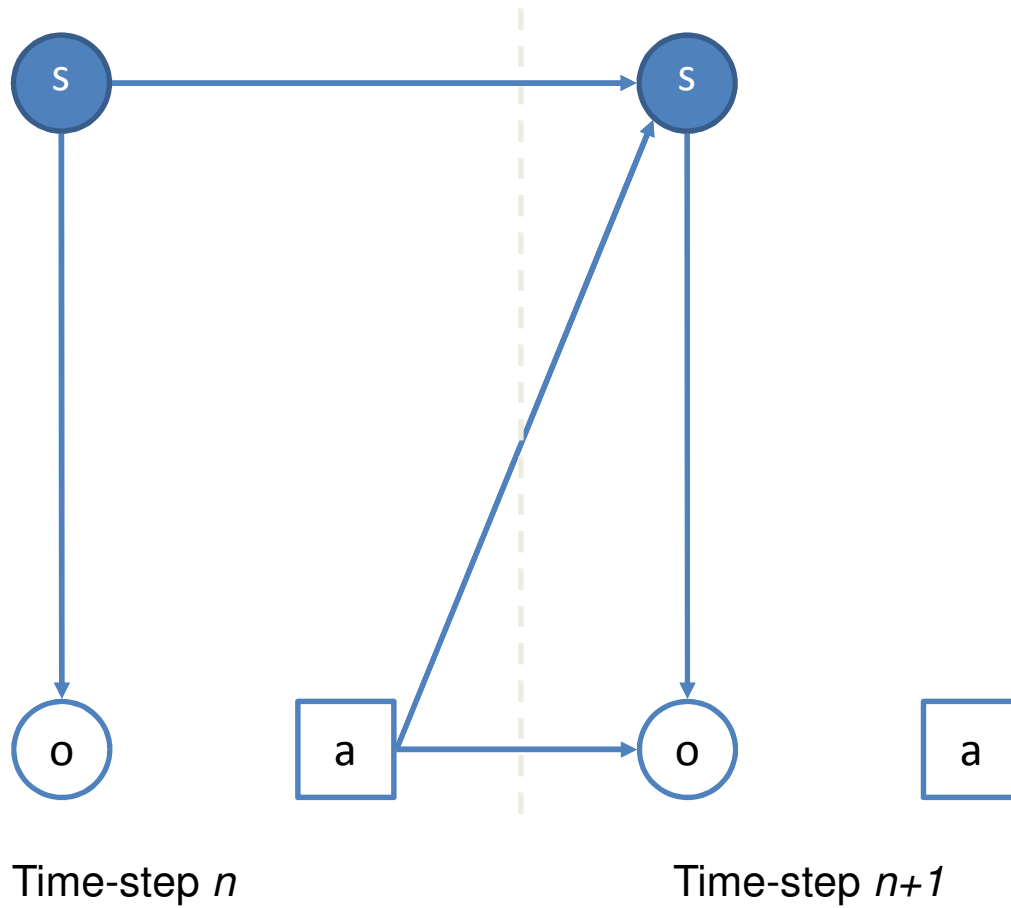
Problems

1. No principled way to encode uncertainty in the dialog
2. No good way to incorporate models of user behavior and ASR errors
3. Actions are chosen locally based on intuition, not globally based on an optimization criteria
4. Good information (N-Best list) is discarded
5. May interact with millions of users, yet will never learn/improve from that experience

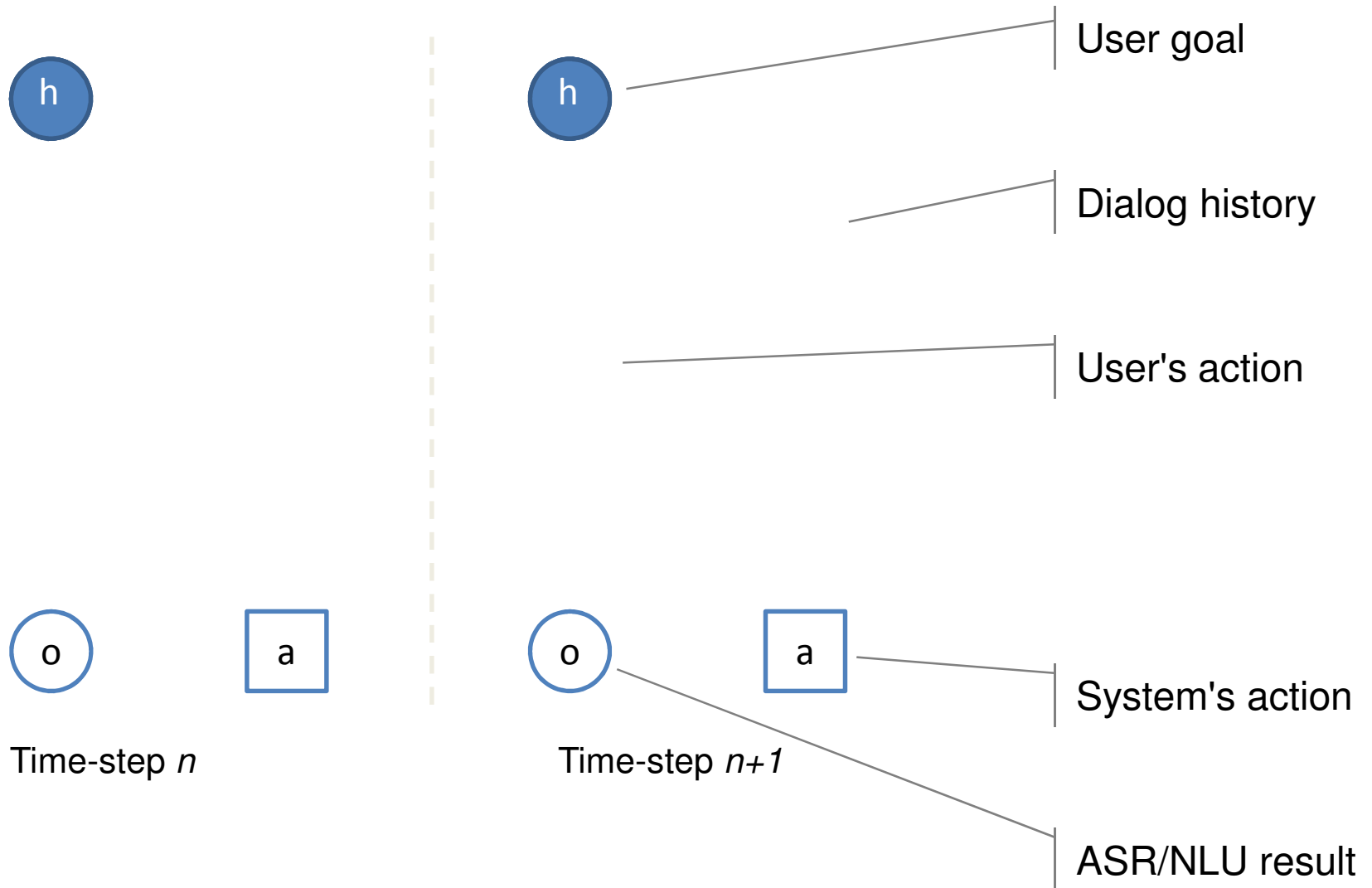
Casting dialog systems as POMDPs

Spoken dialog systems as an application
of POMDPs

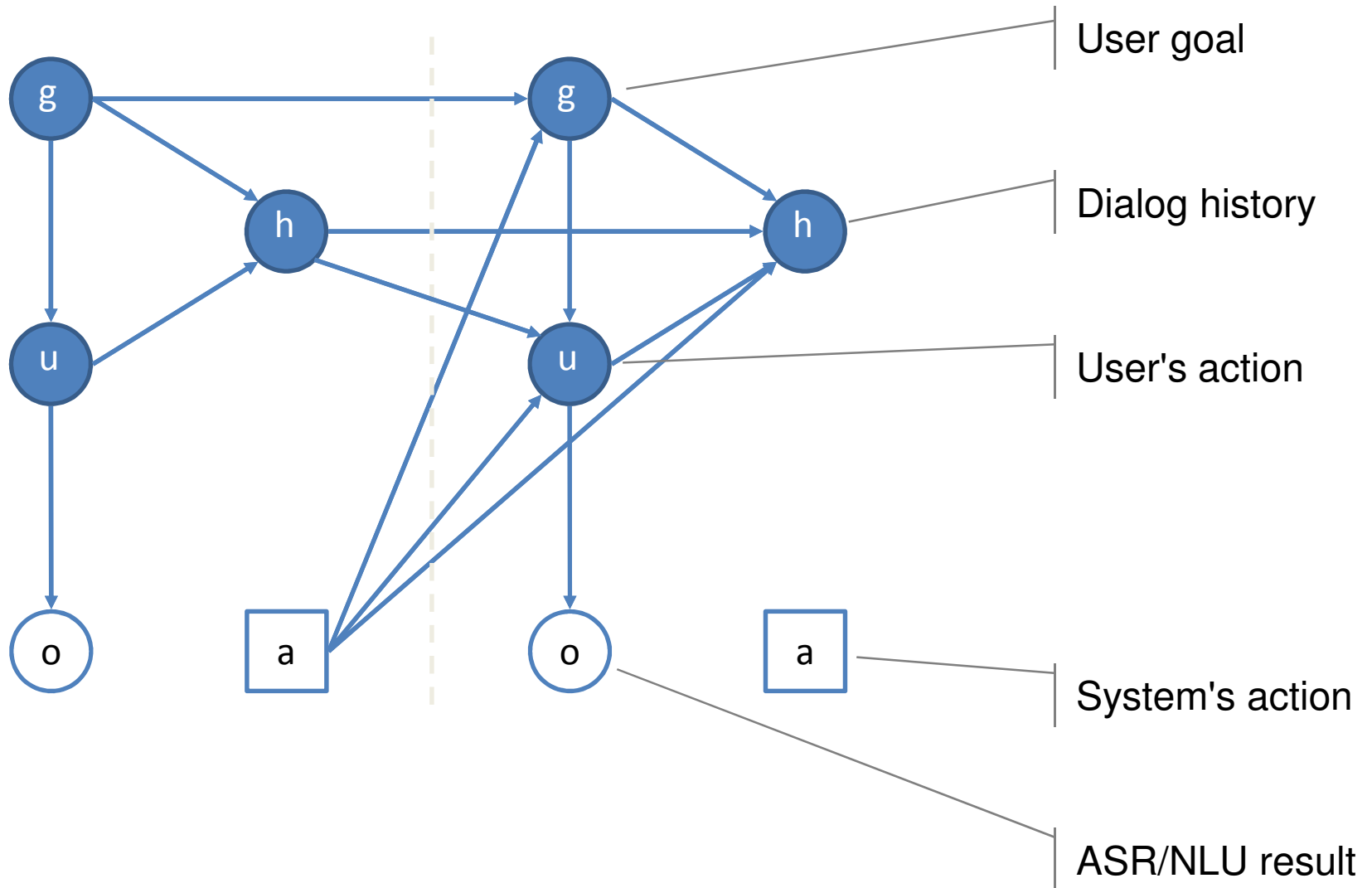
Casting dialog as a POMDP



Casting dialog as a POMDP



Casting dialog as a POMDP



SDS-POMDP update equation

$$b'(g', h') = \eta \cdot \sum_{u'} P(o' | u', a) \sum_h P(u' | g', h, a) P(h' | u', g', h, a) \sum_g P(g' | g, a) b(g, h)$$

The diagram shows the SDS-POMDP update equation with blue brackets and lines connecting terms to their labels:

- $b'(g', h')$ is labeled as "new belief state".
- η is labeled as "normalizing constant".
- $\sum_{u'} P(o' | u', a)$ is labeled as "ASR model".
- $\sum_h P(u' | g', h, a)$ is labeled as "user action model".
- $P(h' | u', g', h, a)$ is labeled as "dialog history model".
- $\sum_g P(g' | g, a)$ is labeled as "user goal model".
- $b(g, h)$ is labeled as "old belief state".

- Assert a reward function $R(s, a)$
- Choose actions to maximize expected sum of rewards over the whole dialog

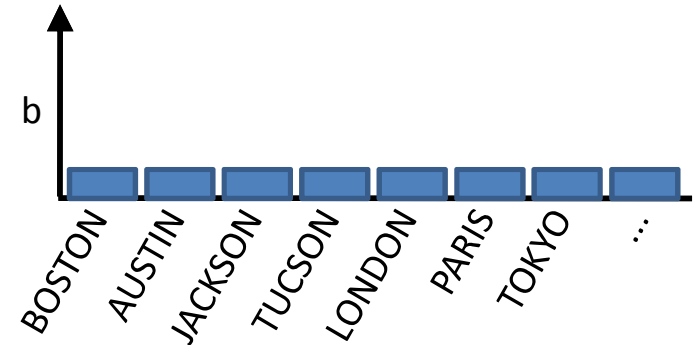
Illustration: synthesizing across N-Best lists

System action

N-Best list

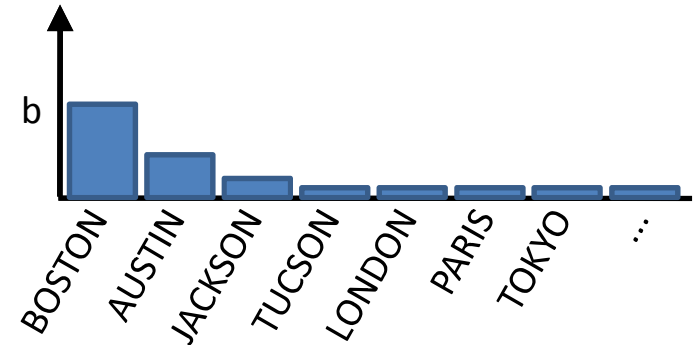
User goal belief

[prior to start of dialog]



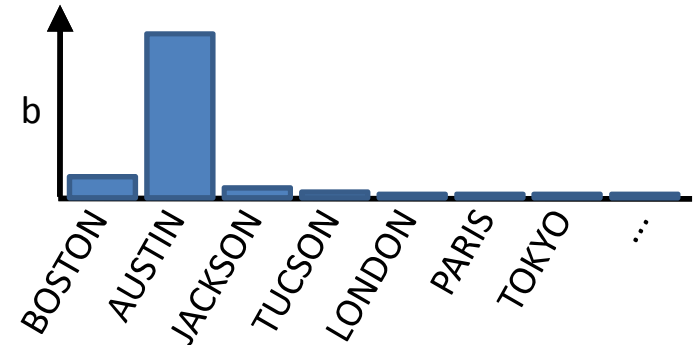
Which city?

BOSTON	~0.50
AUSTIN	~0.20
JACKSON	~0.10

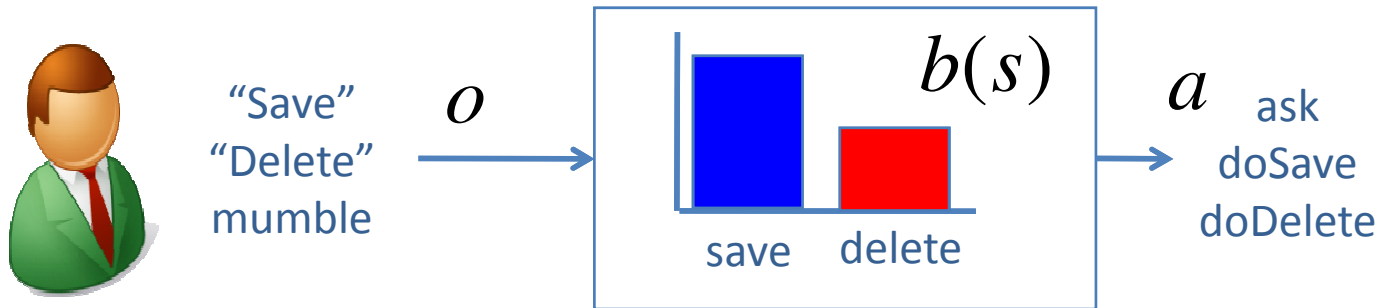


Sorry which city?

TUCSON	~0.20
AUSTIN	~0.10



A Simple Two State Example



Observation Probability

$$P(o' | s', a)$$

eg

"Save"	0.7
"Delete"	0.1
mumble	0.2

$$P(o' | save, ask)$$

Transition Probability

$$P(s' | s, a)$$

	save	delete
save	1.0	0.0
delete	0.0	1.0

$$P(s' | s, ask)$$

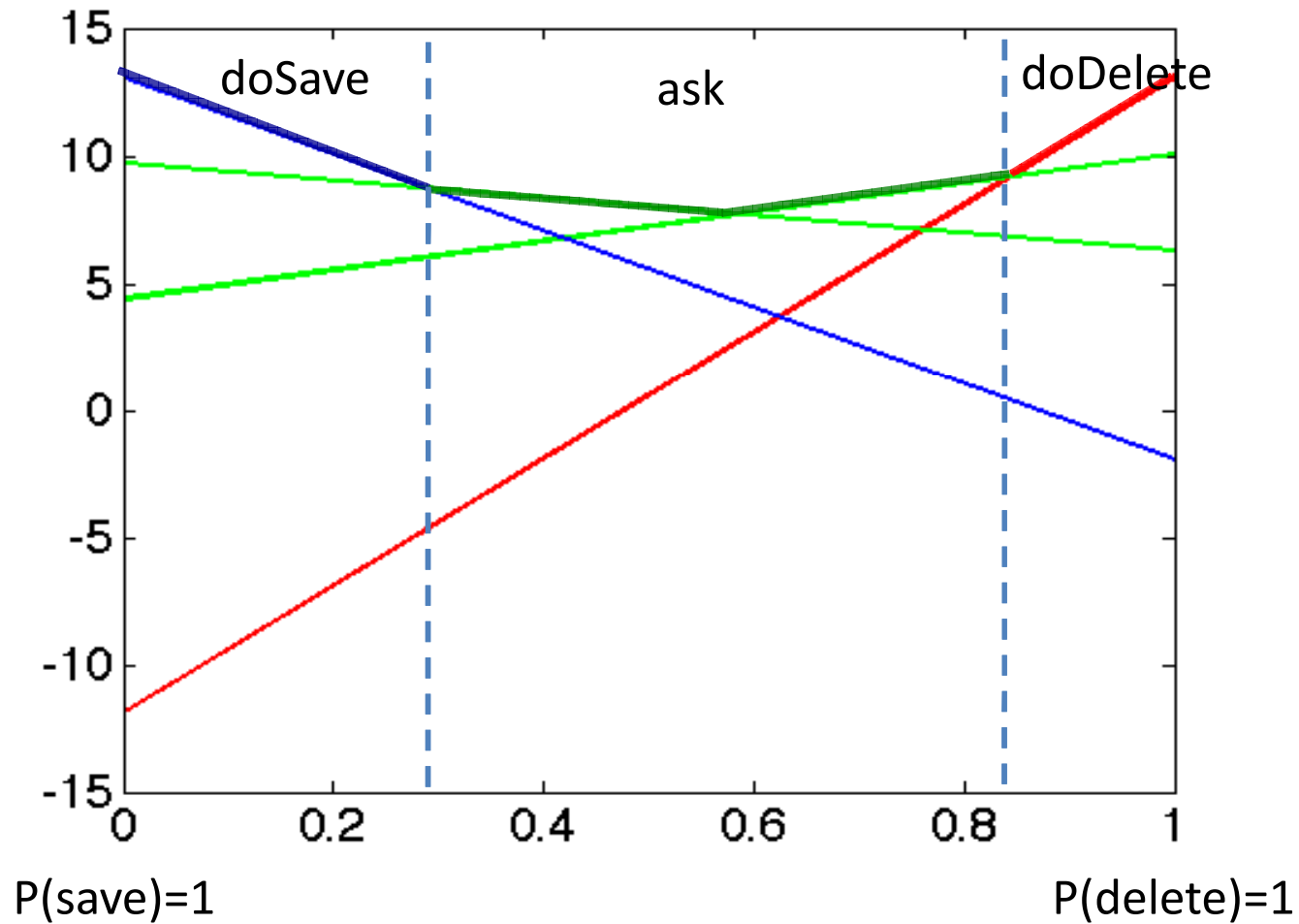
Reward Function

$$R(s, a)$$

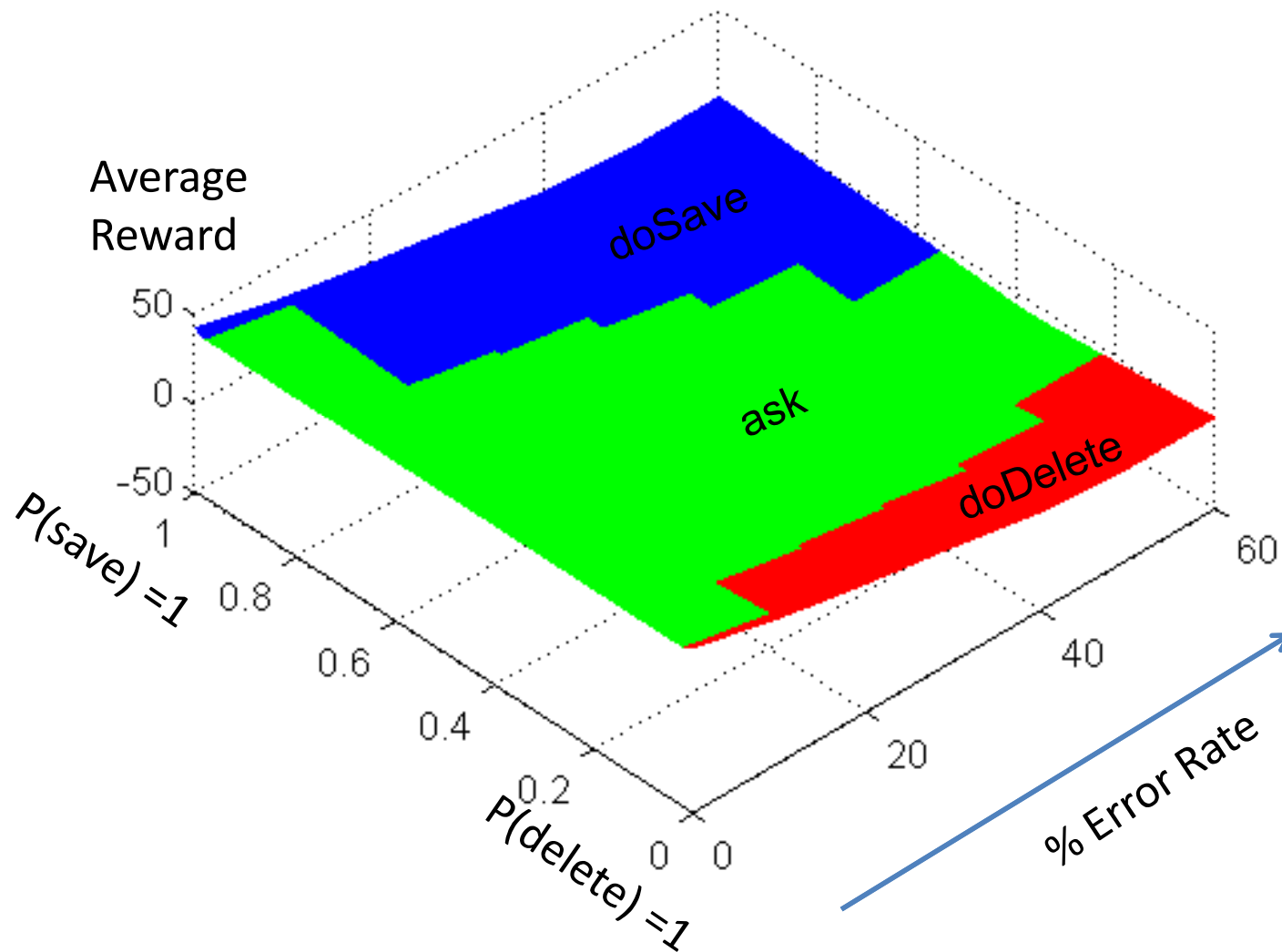
	save	delete
ask	-1	-1
doSave	+5	-10
doDelete	-20	+5

Policy Value Function at 30% Error Rate

Average Return



Policy Value Function vs Error Rate



Growing up to real-world systems

Spoken dialog systems as an application
of POMDPs

Main issues

- 1) Belief update : must run in real-time
- 2) Planning
 - Scalability
 - More sophisticated simulated users
 - Expert knowledge & business rules

Although the dialog problem is well-stated as a POMDP, growing to real-world problems has moved away from traditional POMDP solution algorithms

Problem: Updating belief in real-time

$$b'(g', h') = \eta \cdot \sum_{u'} P(o' | u', a) \sum_h P(u' | g', h, a) P(h' | u', g', h, a) \sum_g P(g' | g, a) b(g, h)$$

new belief state

normalizing constant

ASR model

user action model

dialog history model

user goal model

old belief state

from	1000 values
to	1000 values
time	1000 values
date	1000 values

$$|G| = 1000^4$$

$$= 10^{12}$$

Update is $O(|G|^2) = 10^{24}$

We need a response in < 1 s

$O(10^{24})$ impossible in real time !

2 methods for efficient belief monitoring

1. **M-Best:** Constrain aspects of the model such that un-observed goals can be tracked en-masse
2. **Factorization:** Decompose the network as much as possible; apply approximate inference techniques from the Bayesian network literature

M-Best partitions: Intuition

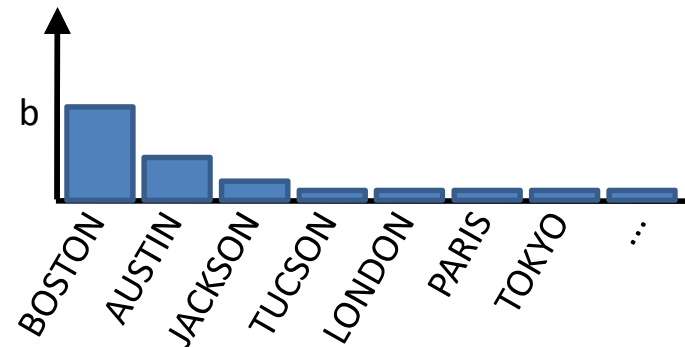
System action

N-Best list

User goal belief

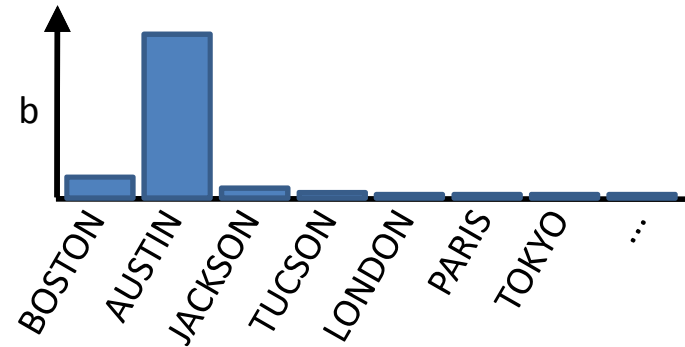
Which city?

BOSTON	~0.50
AUSTIN	~0.20
JACKSON	~0.10



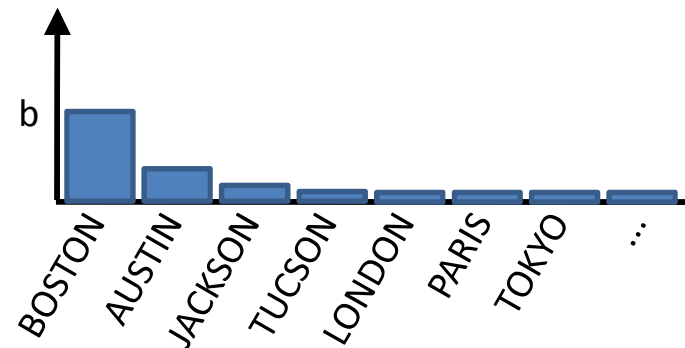
Sorry, which city?

TUCSON	~0.20
AUSTIN	~0.10



Was that Austin?

NO	~0.99
YES	~0.01



M-Best partitions: Intuition

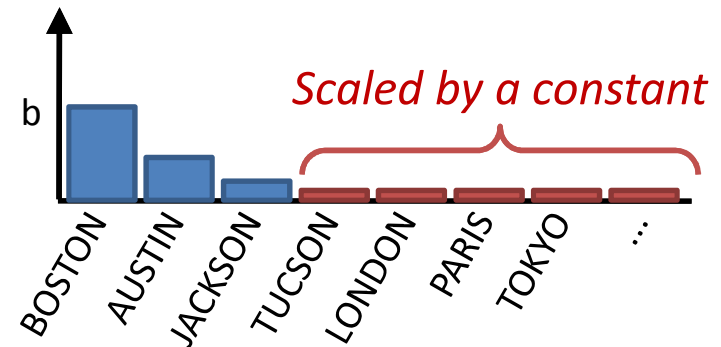
System action

N-Best list

User goal belief

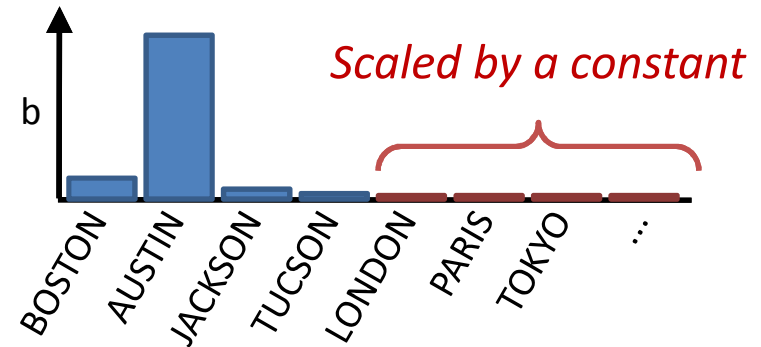
Which city?

BOSTON	~0.50
AUSTIN	~0.20
JACKSON	~0.10



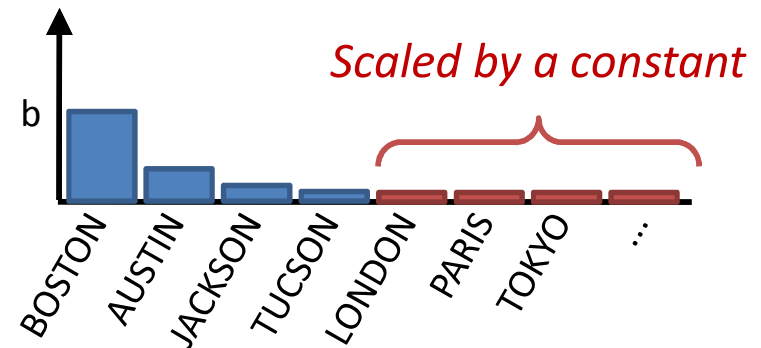
Sorry, which city?

TUCSON	~0.20
AUSTIN	~0.10

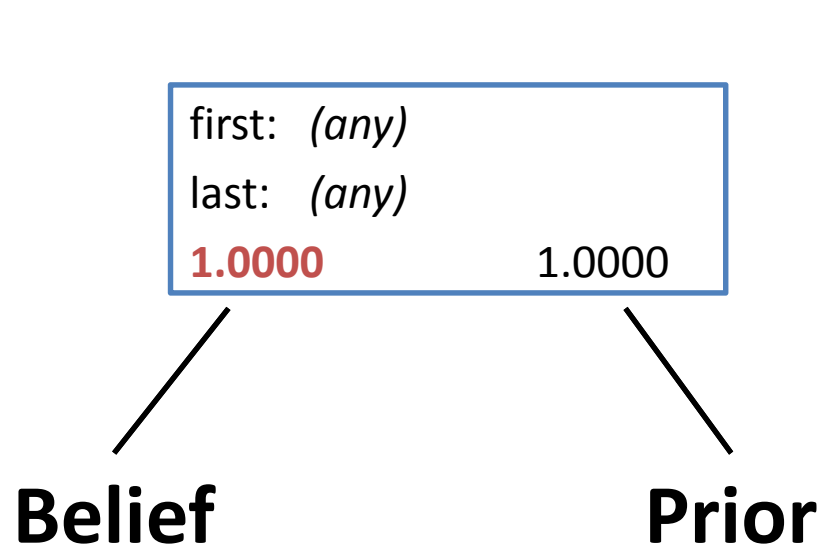


Was that Austin?

NO	~0.99
YES	~0.01



Partition update example (maxPartitions = 3)



"First name?"

JASON ~0.6

Database of priors

First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

Partition update example (maxPartitions = 3)

"First name?"

JASON ~0.6

first: x { jason }
last: (any)
0.9500 0.950

first: jason
last: (any)
0.0500 0.050

First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

Partition update example (maxPartitions = 3)

"First name?"

JASON ~0.6

first: x { jason }
last: (any)
0.0125 0.950

first: jason
last: (any)
0.9875 0.050

First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

Partition update example (maxPartitions = 3)

"First name?"

JASON	~0.6
-------	------

"Last name?"

WILSON	~0.6
WILLIAMS	~0.1

first: x { jason }	
last: (any)	
0.0125	0.950

first: jason	
last: (any)	
0.9875	0.050

First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

Partition update example (maxPartitions = 3)

"First name?"

"Last name?"

first: x { jason }
 last: x { wilson, williams }
0.0119 0.901

JASON ~0.6

WILSON ~0.6
 WILLIAMS ~0.1

first: jason
 last: x { wilson, williams }
0.7702 0.039

first: x { jason }
 last: wilson
0.0001 0.009

first: x { jason }
 last: williams
0.0005 0.040

first: jason
 last: wilson
0.0198 0.001

first: jason
 last: williams
0.1975 0.010

First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

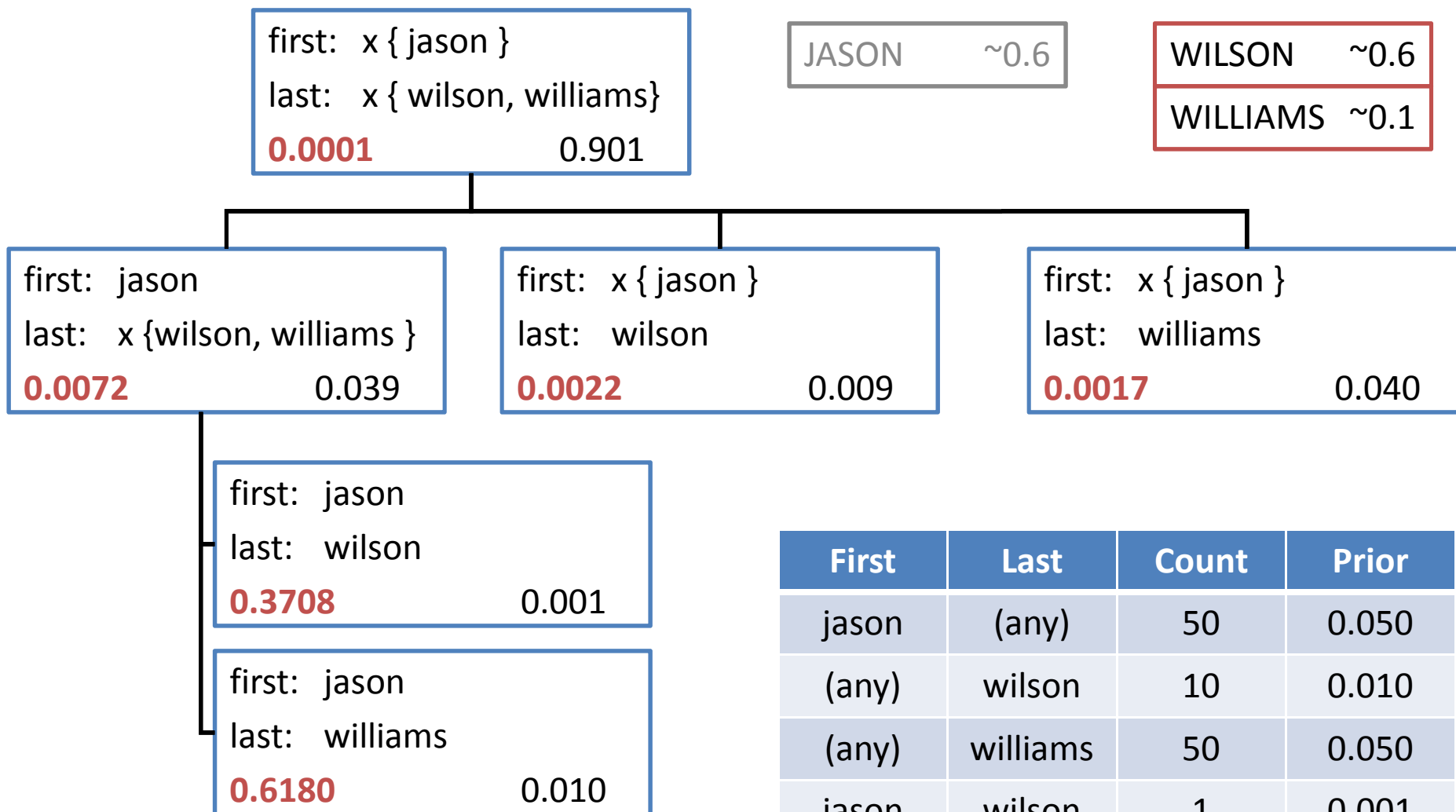
Partition update example (maxPartitions = 3)

"First name?"

JASON ~0.6

"Last name?"

WILSON ~0.6
WILLIAMS ~0.1



First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

Partition update example (maxPartitions = 3)

"First name?"

JASON	~0.6
-------	------

"Last name?"

WILSON	~0.6
WILLIAMS	~0.1

first: x { jason }
 last: x { wilson, williams }
0.0001 0.901

first: jason
 last: x { wilson, williams }
0.0072 0.039

first: x { jason }
 last: wilson
0.0022 0.009

first: x { jason }
 last: williams
0.0017 0.040

first: jason
 last: wilson
0.3708 0.001

first: jason
 last: williams
0.6180 0.010

First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

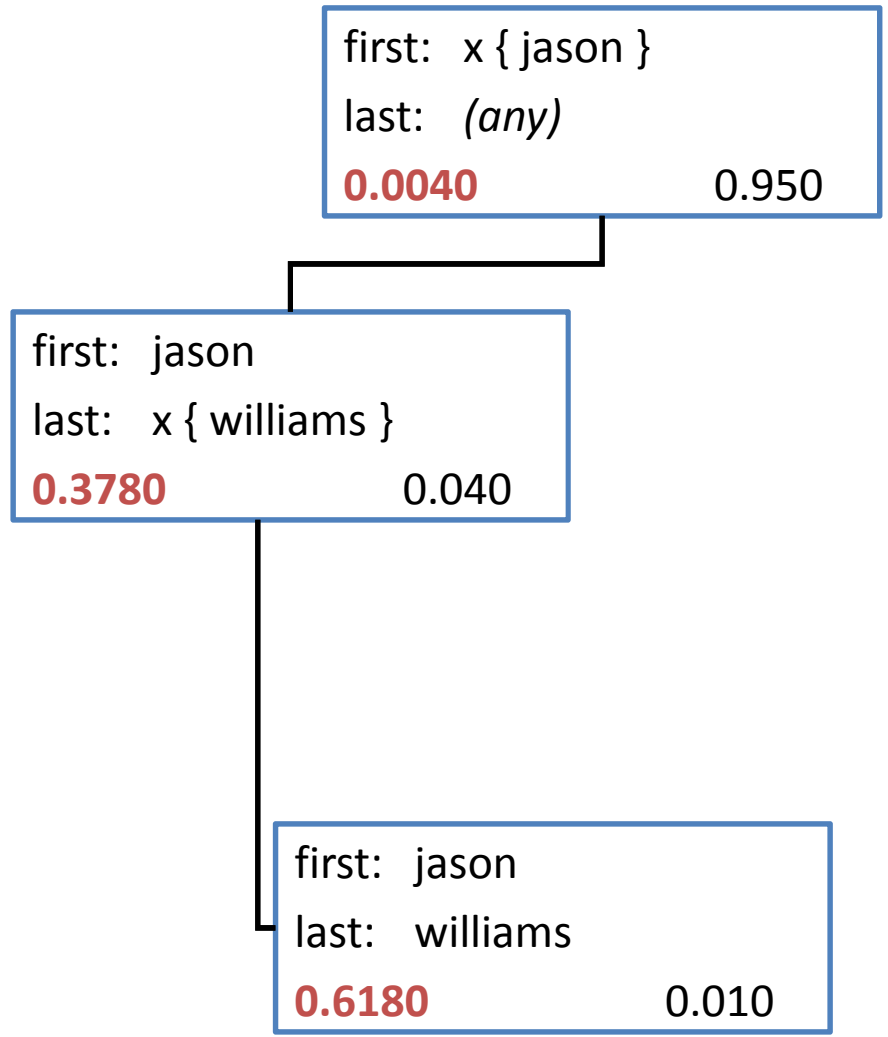
Partition update example (maxPartitions = 3)

"First name?"

JASON	~0.6
-------	------

"Last name?"

WILSON	~0.6
WILLIAMS	~0.1



First	Last	Count	Prior
jason	(any)	50	0.050
(any)	wilson	10	0.010
(any)	williams	50	0.050
jason	wilson	1	0.001
jason	williams	10	0.010

rec

Status █ Time Score HMM NAct Mode

Output

Hello, how may I help you?

THIS: Policy=../resources/...

P/H	Belief	Meaning
1/1	0	

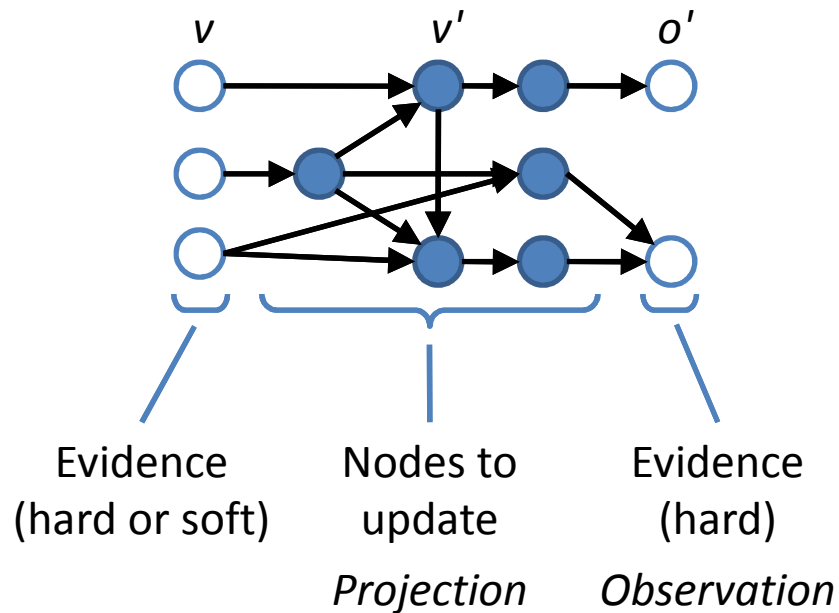
1 Hyps, 1 Parts

hello() [Greet]

aud

Stop HangUp

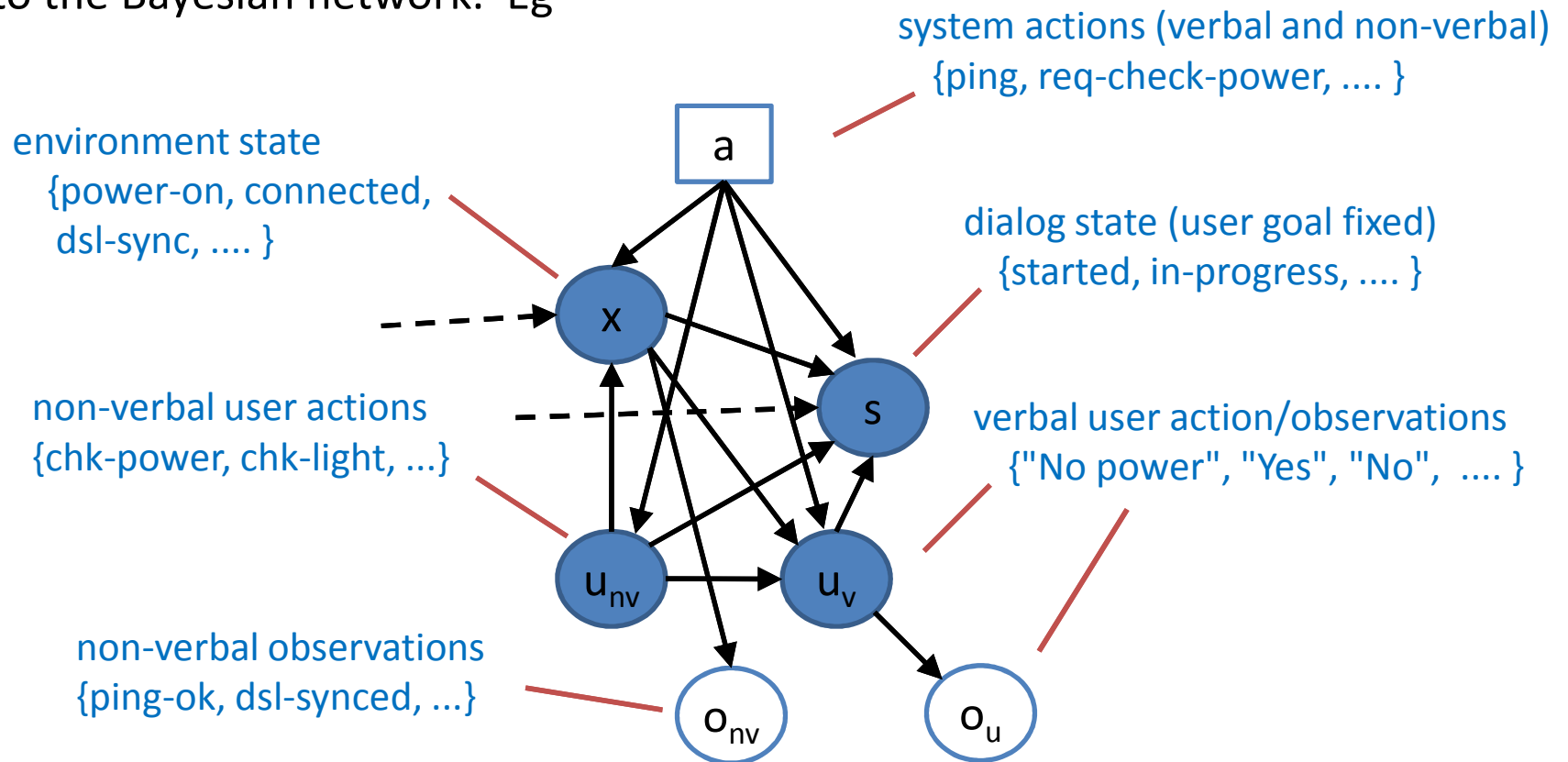
Network-based approaches



Idea: Apply general purpose Bayes Network inference techniques
Approximate inference can be much faster than exact
Examples: loopy belief propagation and particle filters

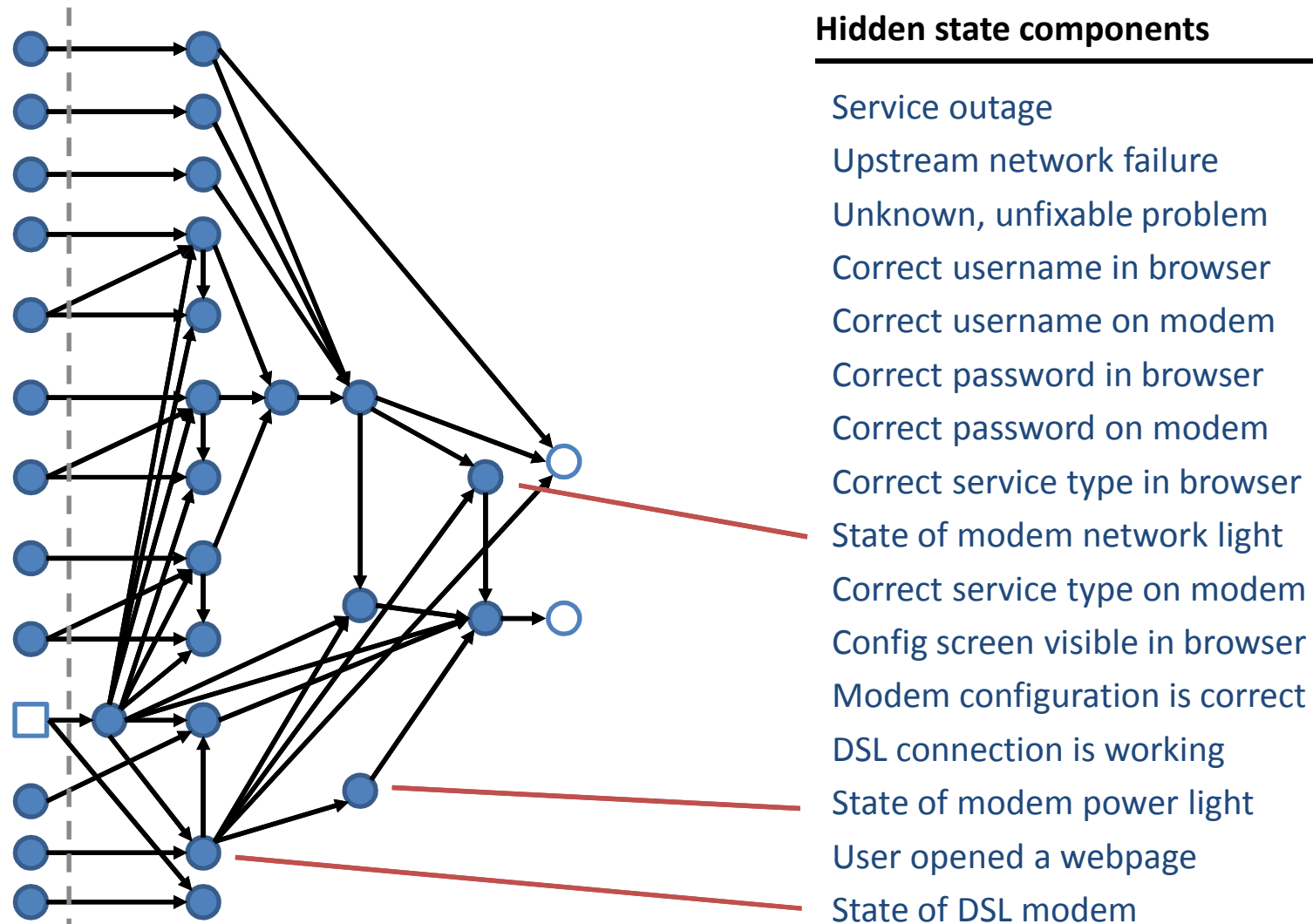
AT&T's Trouble-shooting System

In some applications such as help-lines for DSL modem faults, there are additional sources of uncertainty. These can be easily incorporated into the Bayesian network. Eg



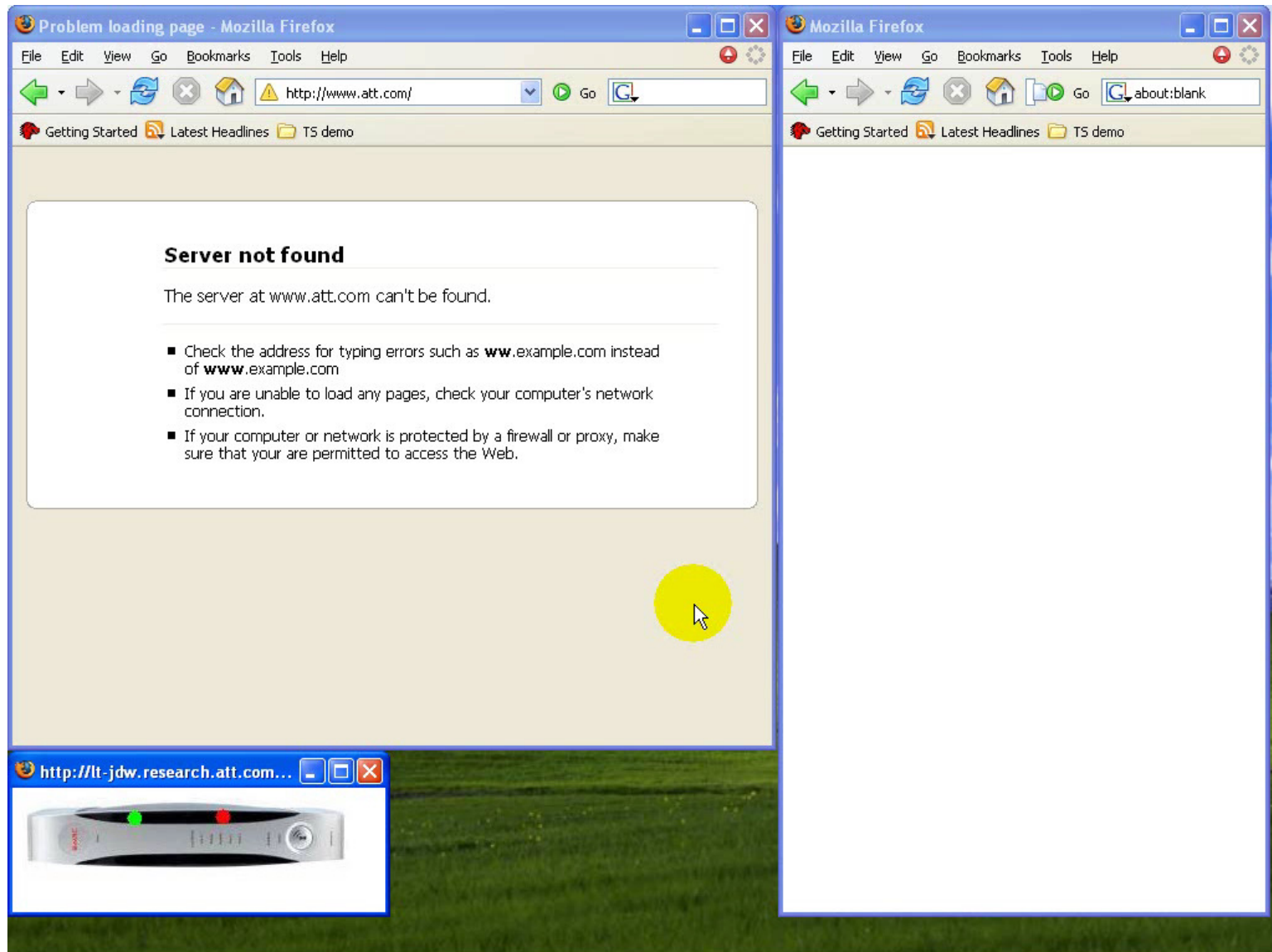
Applying POMDPs to dialog systems in the troubleshooting domain, Williams (Proc W'Shop Bridging the Gap, ACL, 2007)

DSL troubleshooting SDS as a Bayesian network



Applying POMDPs to dialog systems in the troubleshooting domain, Williams (Proc W'Shop Bridging the Gap, ACL, 2007)

Demonstration of AT&T troubleshooting system



Tracking multiple dialogue states: results

		Task completion rates		
	Domain	Single state	Multiple states	
[1]	Higashinaka et al	Room reservation	88%	91%
[2]	Henderson & Lemon	Tourist info	67%	73%
[3]	Young et al	Tourist info	66%	79%
[4]	Thomson & Young	Tourist info	65%	84%

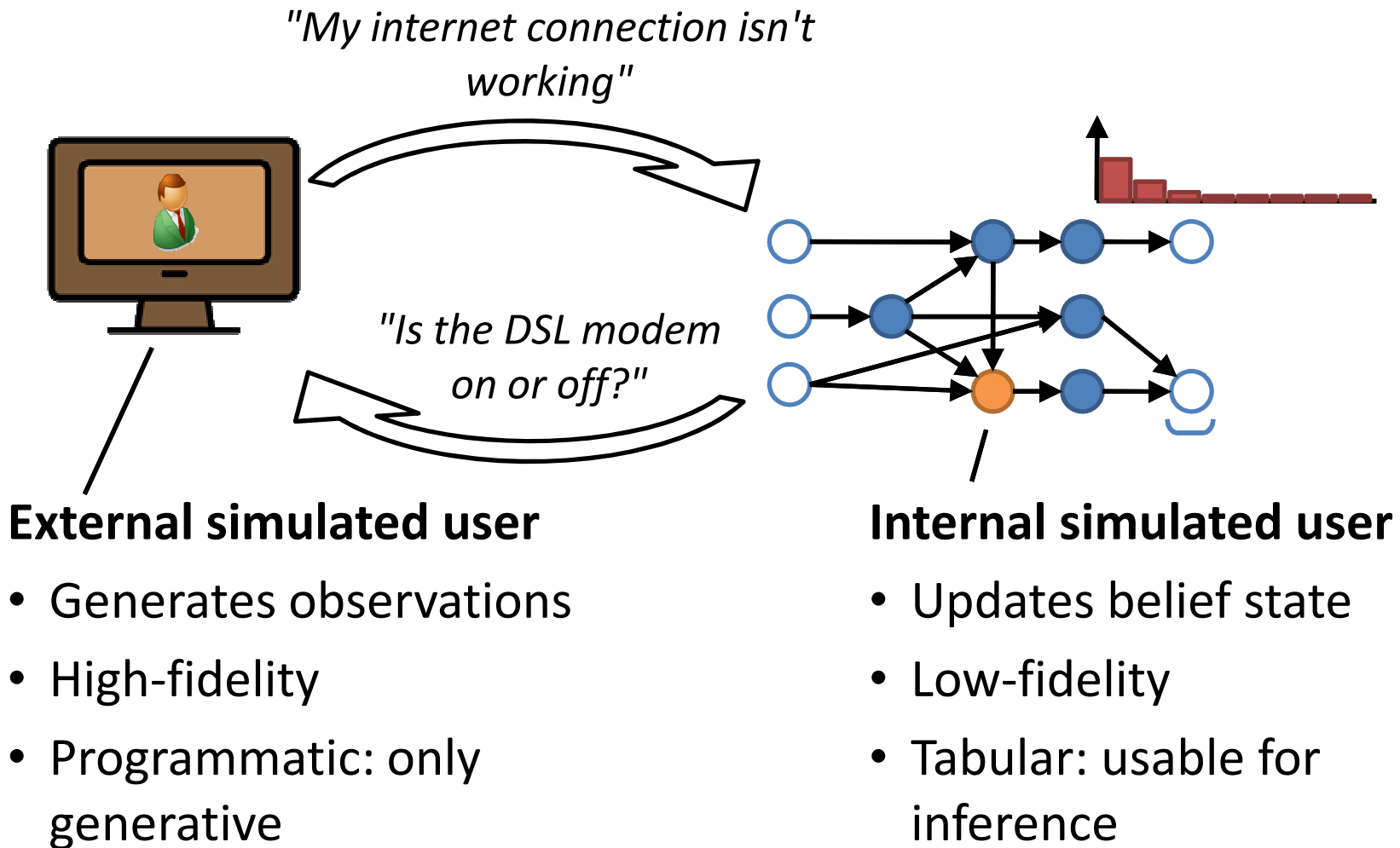
[1] Ryuichiro Higashinaka, Mikio Nakano, Kiyooki Aikawa, "Corpus-based Discourse Understanding in Spoken Dialogue Systems", ACL, pp240-247, 2003

[2] James Henderson and Oliver Lemon, "Mixture Model POMDPs for Efficient Handling of Uncertainty in Dialogue Management", ACL 2008

[3] S. Young, M. Gasic, S. Keizer, F. Mairesse, J. Schatzmann, B. Thomson and K. Yu (2009). "The Hidden Information State Model: a practical framework for POMDP-based spoken dialogue management." Computer Speech and Language, 24(2): 150-174.

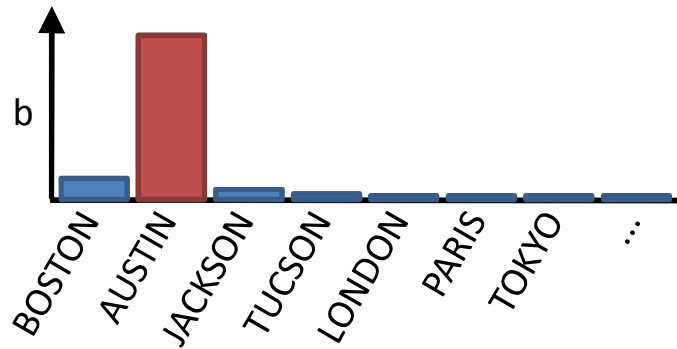
[4] B. Thomson and S. Young (2009). "Bayesian update of dialogue state: A POMDP framework for spoken dialogue systems." Computer Speech and Language, To appear.

Simulated users – two places



To take advantage of high-fidelity user simulation, an external simulation needs to be "in the learning loop"

Planning : what are the difficult decisions?



All possible actions:

ask

confirm(boston)

confirm(austin)

confirm(jackson)

...

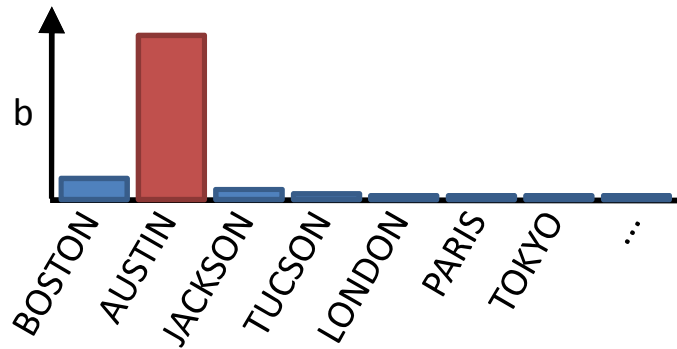
read-weather(boston)

read-weather(austin)

read-weather(jackson)

...

Planning : what are the difficult decisions?



All possible actions:

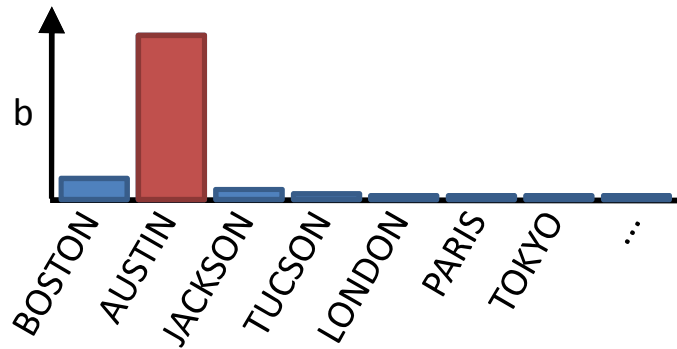
ask
confirm(boston)
confirm(austin)
confirm(jackson)
...
read-weather(boston)
read-weather(austin)
read-weather(jackson)
...

Useful actions:

ask
confirm(boston)
confirm(austin)
confirm(jackson)
...
read-weather(boston)
read-weather(austin)
read-weather(jackson)
...



Planning : what are the difficult decisions?



All possible actions:

ask
confirm(boston)
confirm(austin)
confirm(jackson)
...
read-weather(boston)
read-weather(austin)
read-weather(jackson)
...

Useful actions:

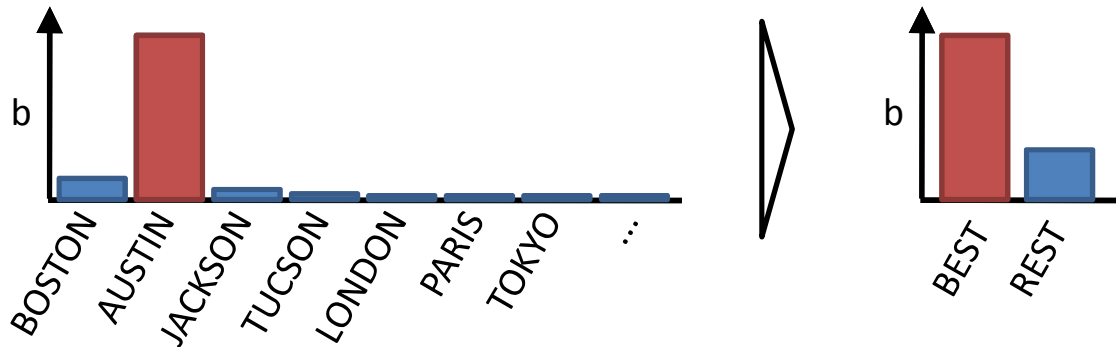
ask
confirm(boston)
confirm(austin)
confirm(jackson)
...
read-weather(boston)
read-weather(austin)
read-weather(jackson)
...

Summary actions:

ask
confirm(best)
read-weather(best)



Planning : what are the difficult decisions?



All possible actions:

ask
confirm(boston)
confirm(austin)
confirm(jackson)
...
read-weather(boston)
read-weather(austin)
read-weather(jackson)
...

Useful actions:

ask
confirm(boston)
confirm(austin)
confirm(jackson)
...
read-weather(boston)
read-weather(austin)
read-weather(jackson)
...

Summary actions:

ask
confirm(best)
read-weather(best)

Domain knowledge & business rules

People know how to build good dialog systems

- The problem is that people can't consider all of the possible situations

Some actions are just silly and shouldn't be explored

- Don't begin the conversation with a confirmation.
- Don't say "Welcome" except at the start
- ...

Guarantees about system performance must be made

- Only allow funds transfer after password is entered

POMDP "Tabula rasa" approach to planning seems inappropriate.
Need a way of incorporating constraints and expert knowledge.

Current approach : Reinforcement learning

- Create a *partial program* which outputs a *set* of one or more acceptable actions
- Extract *features* from the state of the partial program *and* the belief state
- Use RL to choose among the available actions based on the current features

Algorithm	Reference
Natural actor-critic	B. Thomson and S. Young (2010). "Bayesian update of dialogue state: A POMDP framework for spoken dialogue systems." Computer Speech and Language, To appear.
Monte-Carlo sampling	S. Young, M. Gasic, S. Keizer, F. Mairesse, J. Schatzmann, B. Thomson and K. Yu (2009). "The Hidden Information State Model: a practical framework for POMDP-based spoken dialogue management." Computer Speech and Language, 24(2): 150-174. PDF
LSPI w/ feature selection	Lihong Li, Jason D. Williams, and Suhrud Balakrishnan. (2009). Reinforcement Learning for Dialog Management using Least-Squares Policy Iteration and Fast Feature Selection. Proc Interspeech, Brighton, United Kingdom.
SARSA(λ)	J. Henderson, O.Lemon, K.Georgila. (2008). Hybrid reinforcement/supervised learning of dialogue policies from fixed data sets. Computational Linguistics, 34(4):487-511,.
Grid-based value iteration	Jason D. Williams. (2008). Integrating expert knowledge into POMDP optimization for spoken dialog systems. Proc AAAI Workshop on Advancements in POMDP Solvers, Chicago, USA.
Q-MDP	J. Henderson and O.Lemon. (2008). Mixture model POMDPs for efficient handling of uncertainty in dialogue management. In Proc. 46th Annual Meeting of the Association for Computational Linguistics (ACL'08), Columbus, Ohio.

POMDP Dialer : call from 2123874000

Previous system action

Sorry, first and last name?

Recognition result

50 jason williams florham_park nj
 jason williams florham_park nj usa

Belief State

Remaining mass [0 partition(s)]

jason williams florham_park, nj (usa)
jason fong columbia, md (usa)
juan dong north_sydney, au (iaus)
jason downing sacramento, ca (usa)
jason kan englewood, co (usa)
jason hendrix houston, tx (usa)
zhesheng huang middletown, nj (usa)

State Features

Best name
 Best phone type
 Phones available both
 Name confirmed? no
 Name is ambiguous? no

Allowed Actions

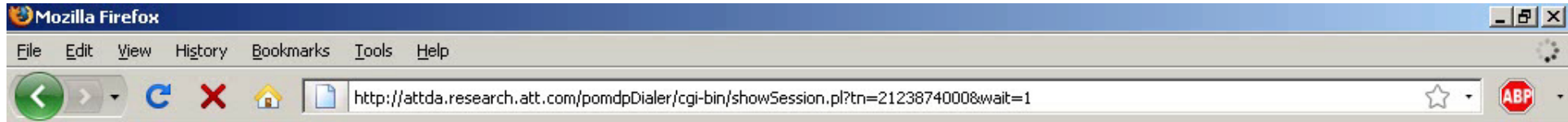
AskName Sorry, first and last name?
AskPhoneType jason d williams florham_park new jersey. Say office, cell, or cancel.

Action Search

Values at point 51 (distance 0.028)
18.511 AskPhoneType
 17.806 ConfirmPhoneType
 17.546 AskName

Output system action

jason d williams florham_park new jersey. Say office, cell, or cancel.



Please call 1-888-298-8206

Waiting for call from 2123874000...

Reinforcement Learning: results

	Domain	Task completion Baseline	RL
[1] Singh et al, 2002	Tourist info	20-64%	88%
[2] Lemon et al, 2006	Tourist info	68%	82%
[3] Frampton & Lemon, 2008	Tourist info	82%	91%
[4] Young et al, 2009	Tourist info	64%	79%
[5] Thomson & Young, 2009	Tourist info	84%	75%
[6] Cuayahuitl et al, 2010	Flight booking	94%	95%

[1] S Singh, DJ Litman, M Kearns, and M Walker, "Optimizing dialogue management with reinforcement learning: Experiments with the NJFun system," Journal of Artificial Intelligence Research, 2002.

[2] Oliver Lemon, Kallirroi Georgila, James Henderson, "Evaluating Effectiveness and Portability of Reinforcement Learned Dialogue Strategies with real users: the TALK TownInfo Evaluation", IEEE/ACL Spoken Language Technology, 2006.

[3] Matthew Frampton and Oliver Lemon. 2008. Using dialogue acts to learn better repair strategies. Proc ICASSP 2008.

[4] S. Young, M. Gasic, S. Keizer, F. Mairesse, J. Schatzmann, B. Thomson and K. Yu (2009). "The Hidden Information State Model: a practical framework for POMDP-based spoken dialogue management." Computer Speech and Language, 24(2): 150-174.

[5] B. Thomson and S. Young (2009). "Bayesian update of dialogue state: A POMDP framework for spoken dialogue systems." Computer Speech and Language, To appear.

[6] Heriberto Cuayahuitl, Steve Renals, Oliver Lemon, Hiroshi Shimodaira, "Evaluation of a hierarchical reinforcement learning spoken dialogue system", Computer Speech and Language, (to appear)

Some thoughts on the future

Spoken dialog systems as an application
of POMDPs

What happened to POMDPs?

The problem is definitely a POMDP...

... but current solutions do not apply (what we call)
"POMDP algorithms"

Are there useful learnings for developers of POMDP
algorithms?

A wish-list for POMDP algorithm developers

- **Lifted POMDPs:** Can inference *and planning* be done in a lifted (first-order logic) space?
- **Designer knowledge:** Are there good ways of incorporating designer knowledge into planning?
- **High-fidelity simulations:** Is there a principled way they can be incorporated into optimization?
- **POMDPs and standard programming languages:** Is there a good toolkit based on Python or Java?

If you want to get started...

Some tools are available:

- **AT&T Statistical Dialog Toolkit**

Efficiently track multiple dialog states

www.research.att.com/people/Williams_Jason_D

- **AT&T Speech Mash-ups**

Speech recognition & synthesis "in the cloud"

<https://service.research.att.com/smm>

Thanks!

Jason D. Williams

Spoken dialog systems as an
application of POMDPs



ICAPS Workshop – May 2010